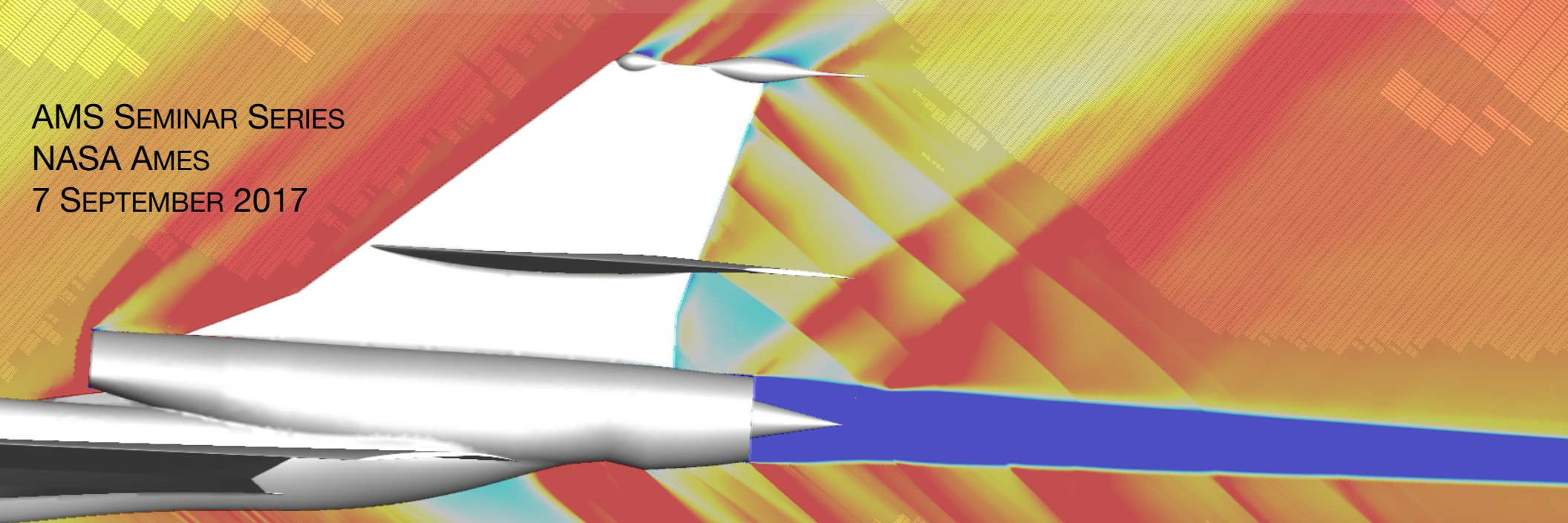


CART3D SIMULATIONS

FOR THE 2ND AIAA SONIC BOOM PREDICTION WORKSHOP

AMS SEMINAR SERIES
NASA AMES
7 SEPTEMBER 2017



George R. Anderson

Science & Technology Corp.

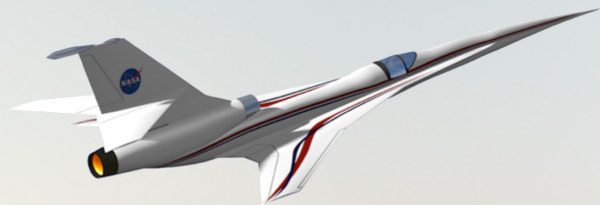
Michael J. Aftosmis

NASA Ames

Marian Nemec

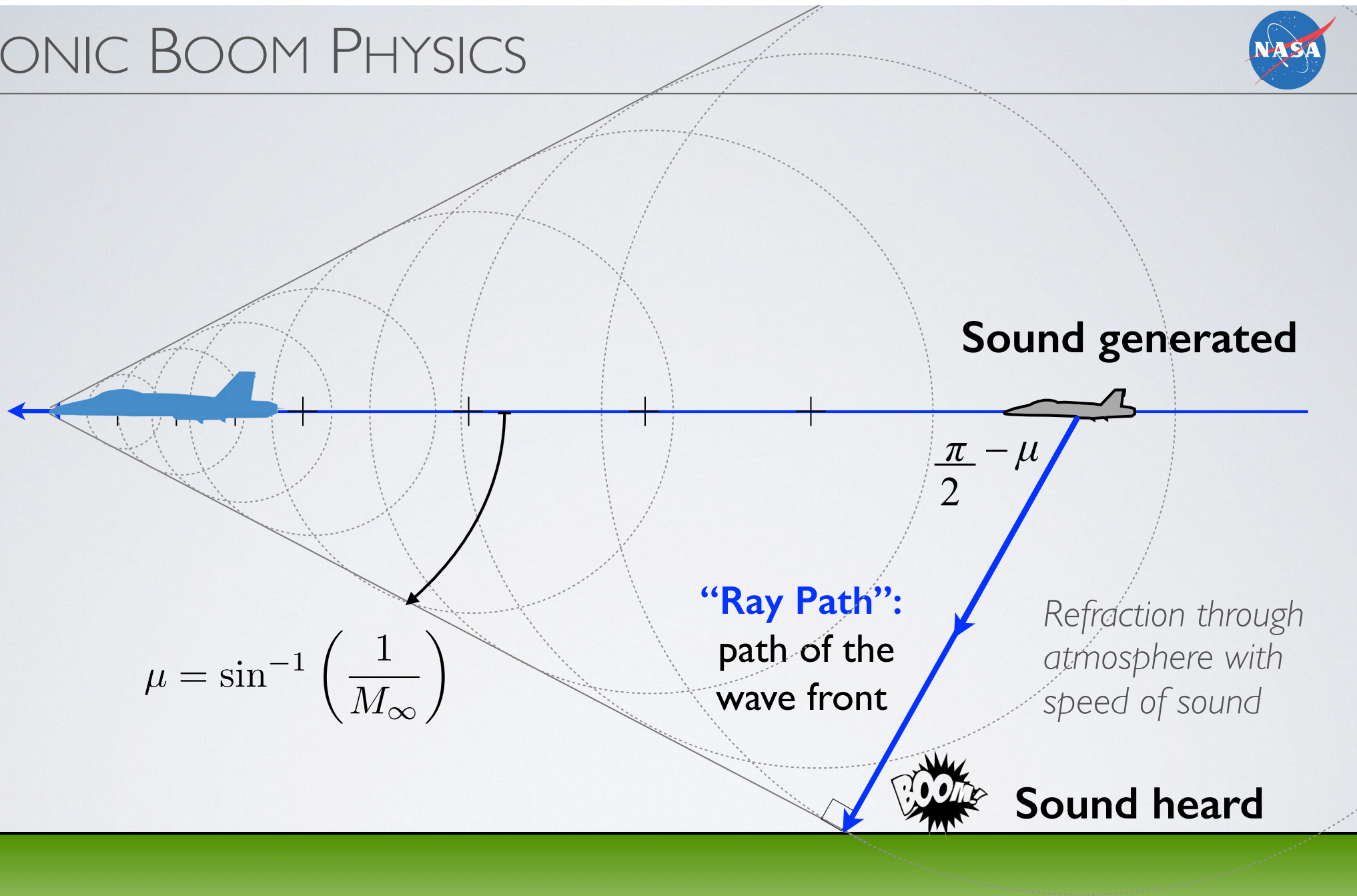
NASA Ames

Computational Aerosciences Branch
NASA ARC — Moffett Field, CA

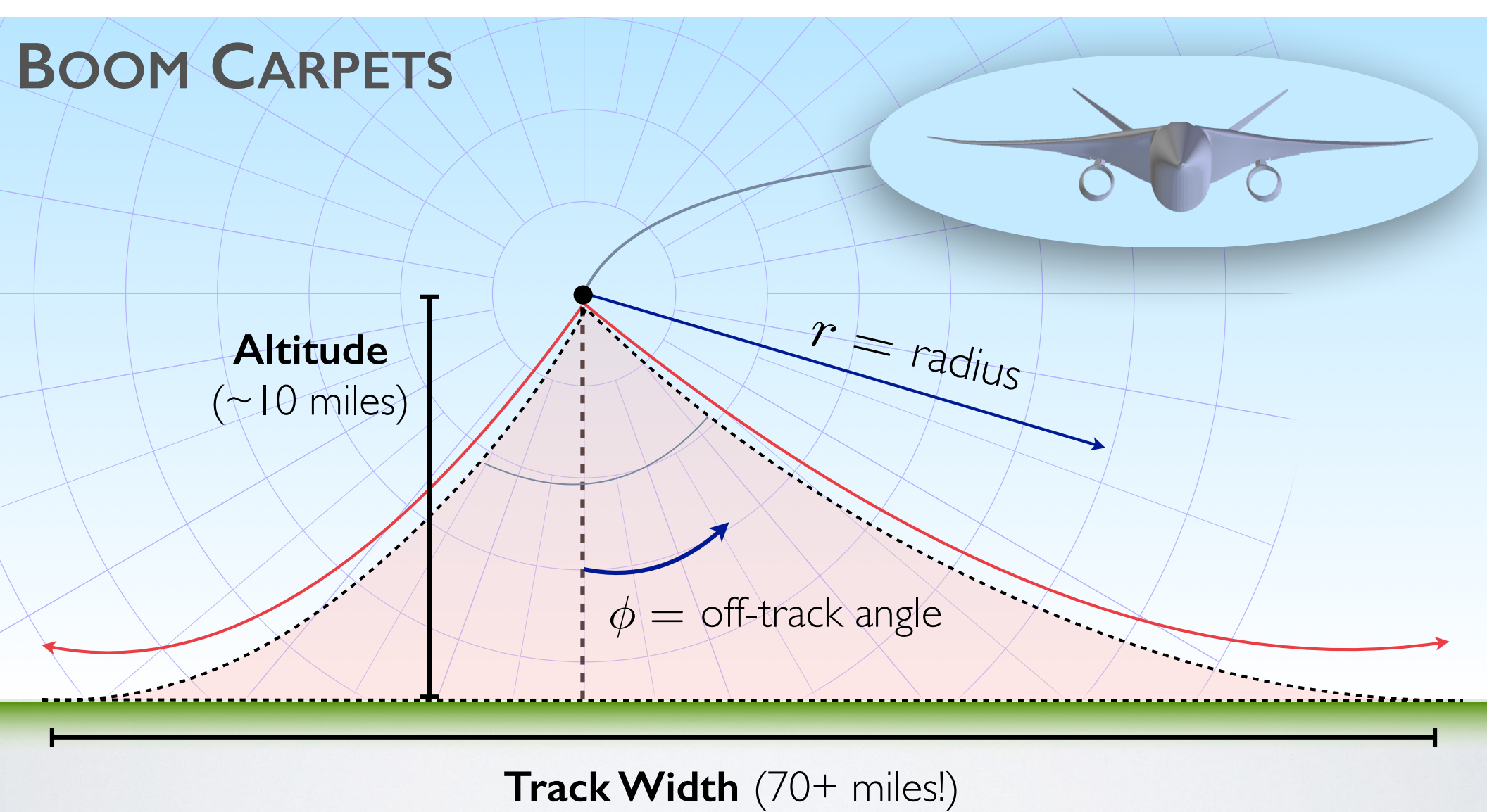


- **Commercial supersonic flight** banned over the US because of objectionable sonic boom
- Hope to overturn this with demonstrably quiet aircraft (e.g. QueSST/LBFD)
- **CFD tools are a major contributor to design efforts**
- Sonic Boom Prediction Workshops
 - (2008) NASA FAP SBPW
 - (2014) AIAA SBPW1
 - **(2017) AIAA SBPW2**

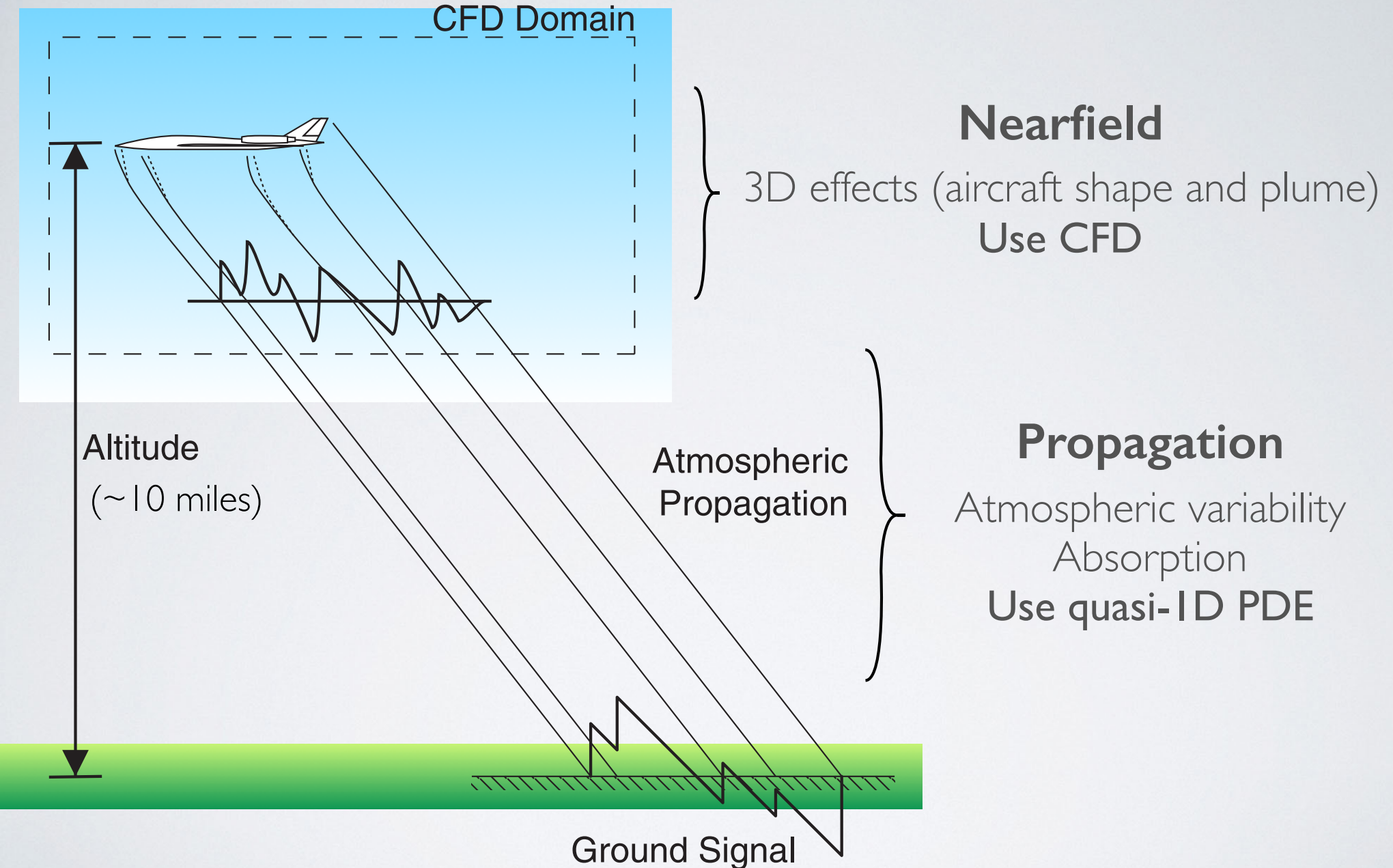
SONIC BOOM PHYSICS



BOOM CARPETS



SONIC BOOM PREDICTION



NEARFIELD CASES

AXIE

JWB

C25F

C25P

ALL CASES:
MACH 1.6
Altitude: 15.76 km
(~52K feet)

NEARFIELD CASES

AXIE

JWB

C25F

C25P

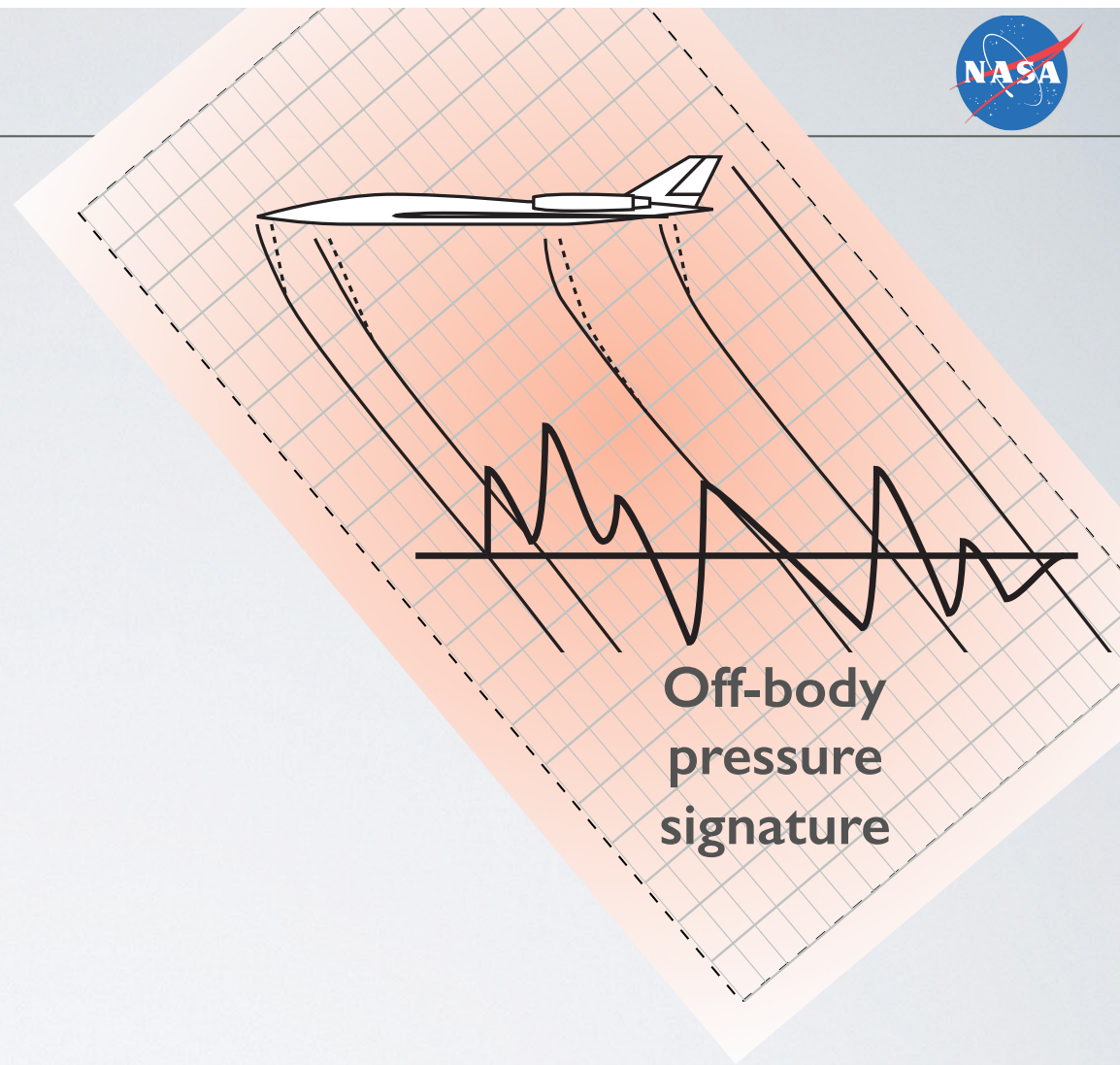
Today

ALL CASES:
MACH 1.6
Altitude: 15.76 km
(~52K feet)

▶ **Nearfield Workshop — Cart3D**

- **Meshing approach** — Mach Alignment + Adaptation
- **Boom Carpets** — Azimuthal Alignment
- **Results** for Cases 1 and 4
- **Local Error Analysis**

- Propagation Workshop
- Full Vehicle-to-Boom Simulation Path
- Conclusions



CFD AND MESHING

Flow Solver — Cart3D v1.5

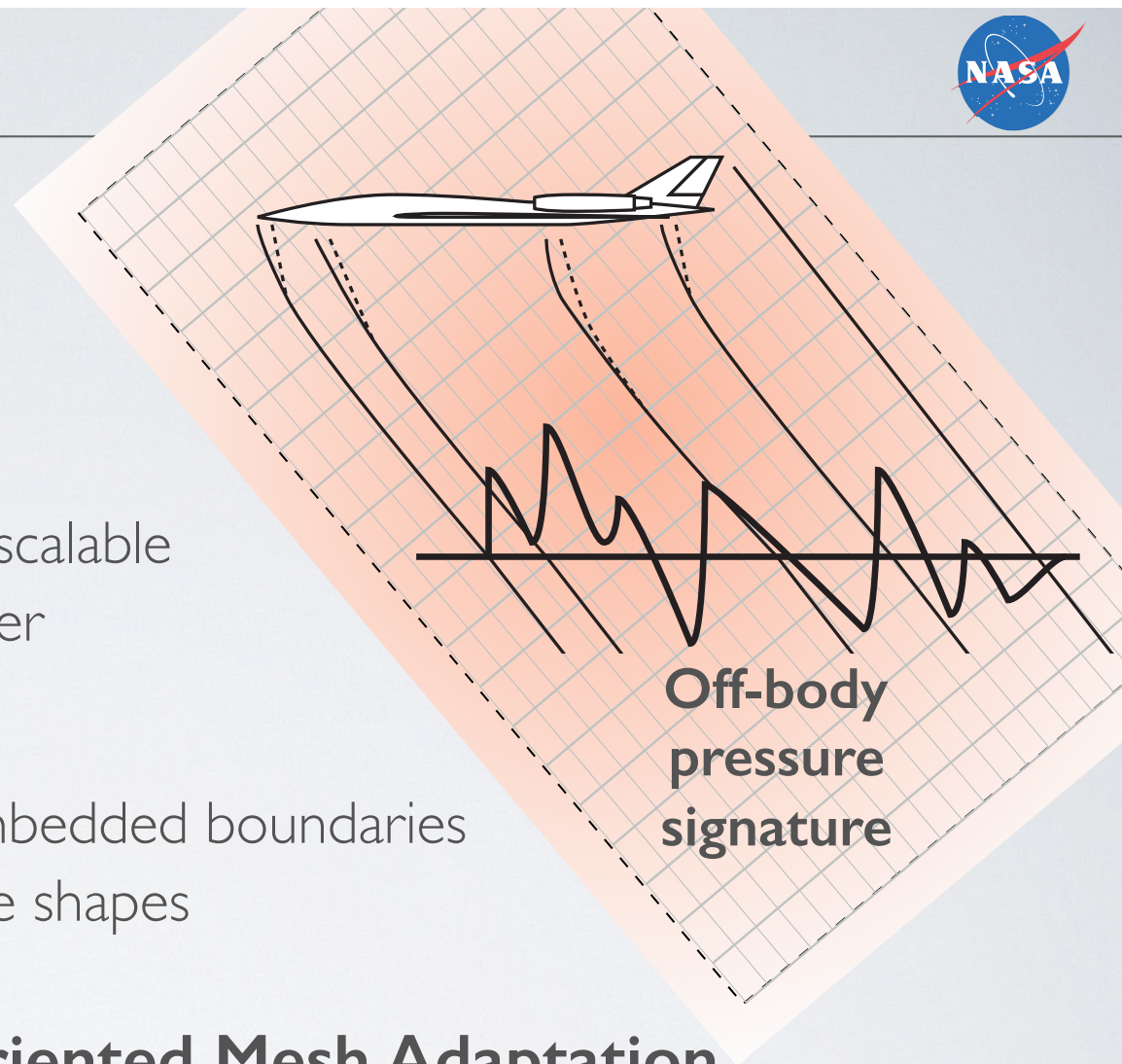
- ▶ Steady, inviscid flow
- ▶ 2nd-order upwind method
- ▶ Multigrid acceleration
- ▶ Domain decomposition — highly scalable
- ▶ *For this work:* Barth-Jespersen limiter

Automatic Meshing

- ▶ Multilevel Cartesian mesh with embedded boundaries
- ▶ Handles arbitrarily complex vehicle shapes

Error Estimation and Goal-Oriented Mesh Adaptation

- ▶ Discretization error estimates computed via method of adjoint-weighted residuals
- ▶ Mesh automatically refined in locations with most impact on signatures



**Off-body
pressure
signature**



AXIE

$M_\infty = 1.6$
 $\alpha = 0^\circ$

$$\sin^{-1} \left(\frac{1}{M_\infty} \right) + 0.5^\circ$$

Offset to avoid
"sonic glitch"

$r/L = 1$

$r/L = 3$

$r/L = 5$

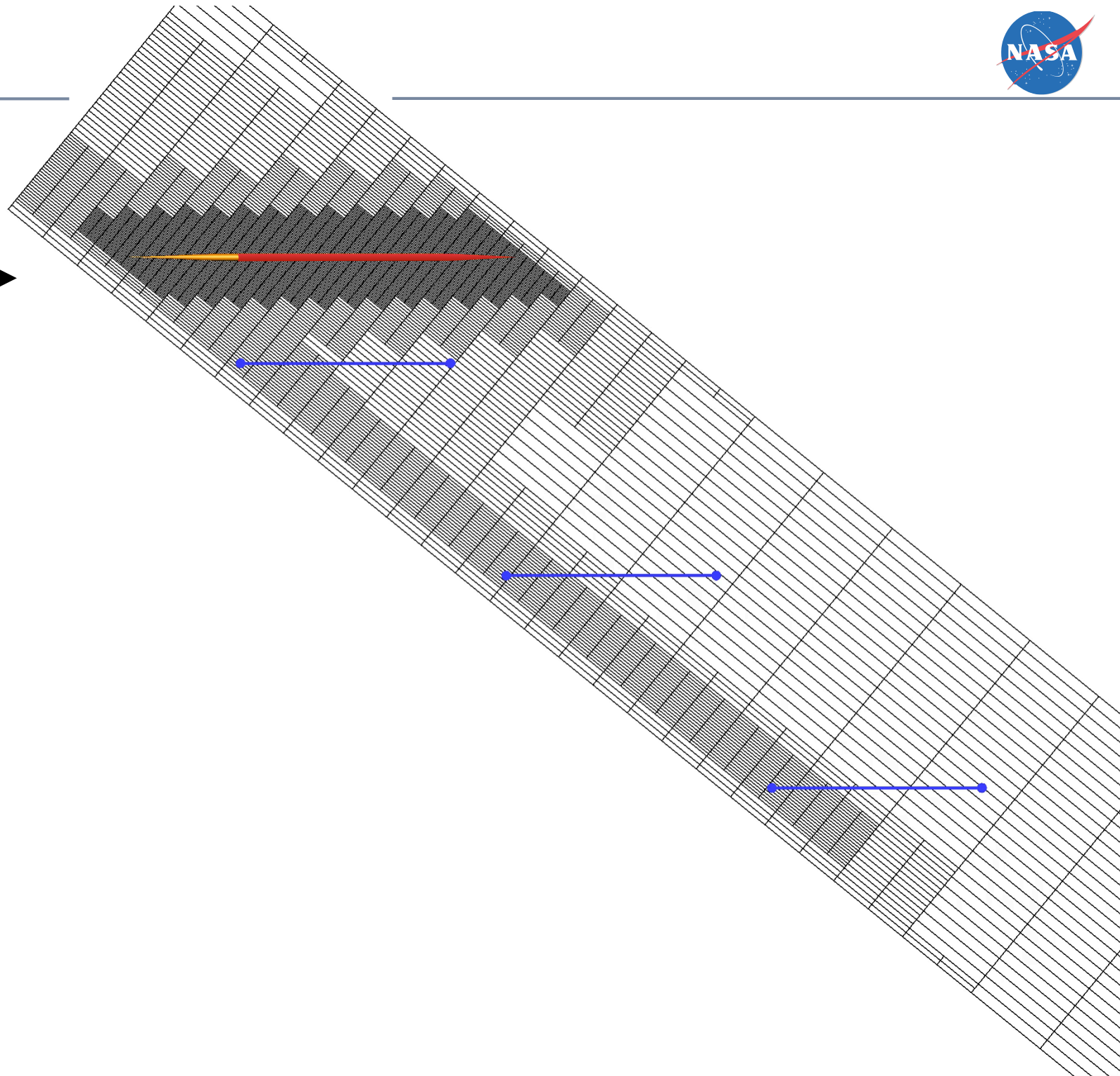
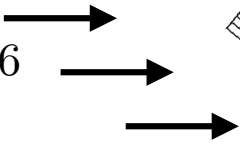
Level 0 mesh
22K cells

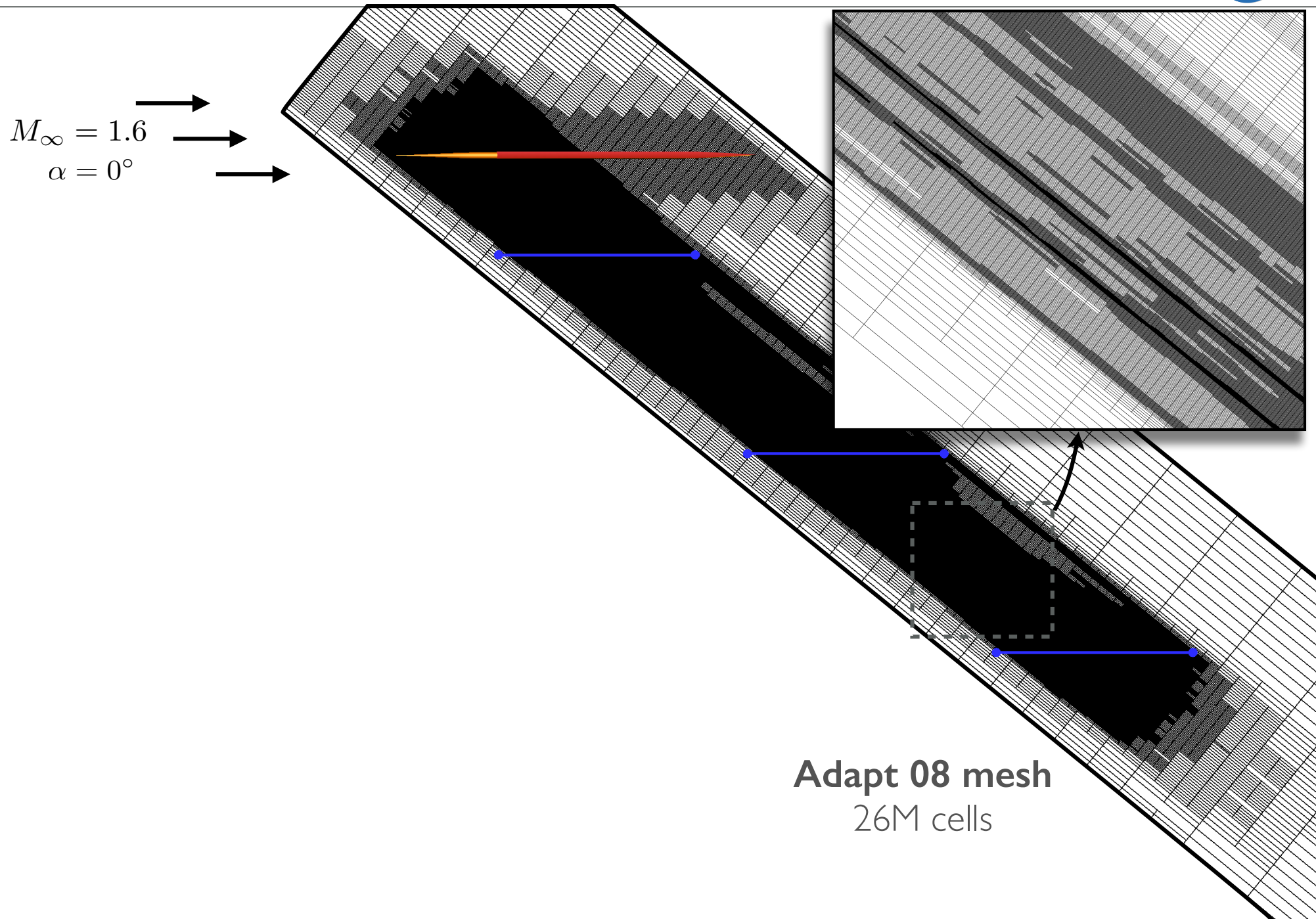
Basic Meshing Approach:

1. **Rotate** mesh very close to the Mach angle
2. **Stretch** in the principal propagation direction
3. **Adapt** mesh to resolve line sensor outputs
(method of adjoint-weighted residuals)

$$\mathcal{J}_r = \int_0^L w(\ell) \left(\frac{p(\ell) - p_\infty}{p_\infty} \right)^2 d\ell$$

$M_\infty = 1.6$
 $\alpha = 0^\circ$



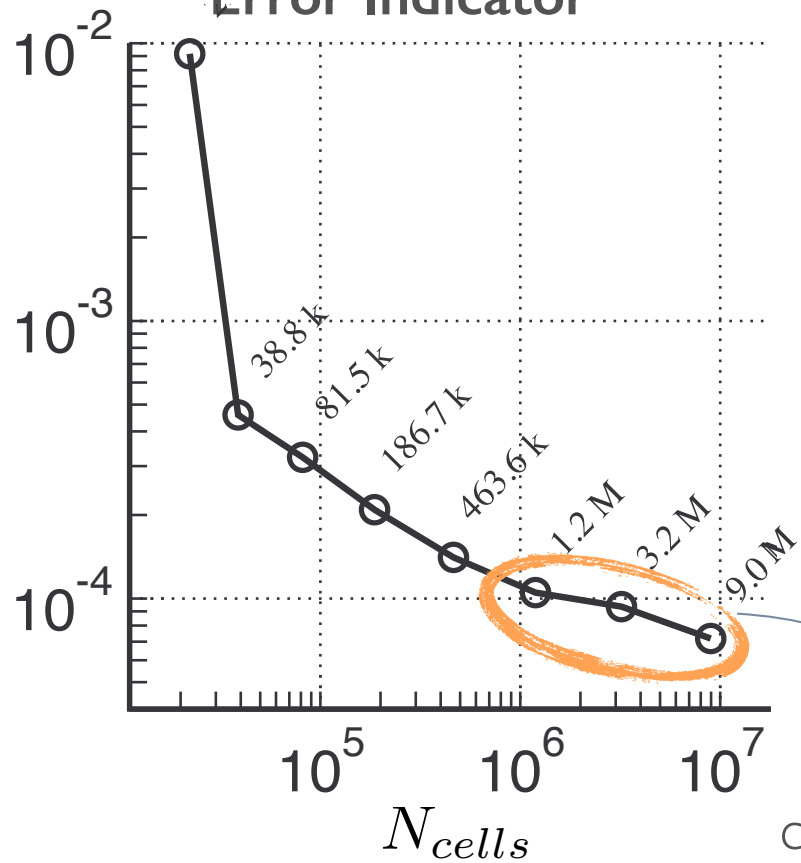


ADAPTATION

$$M_{\infty} = 1.6$$

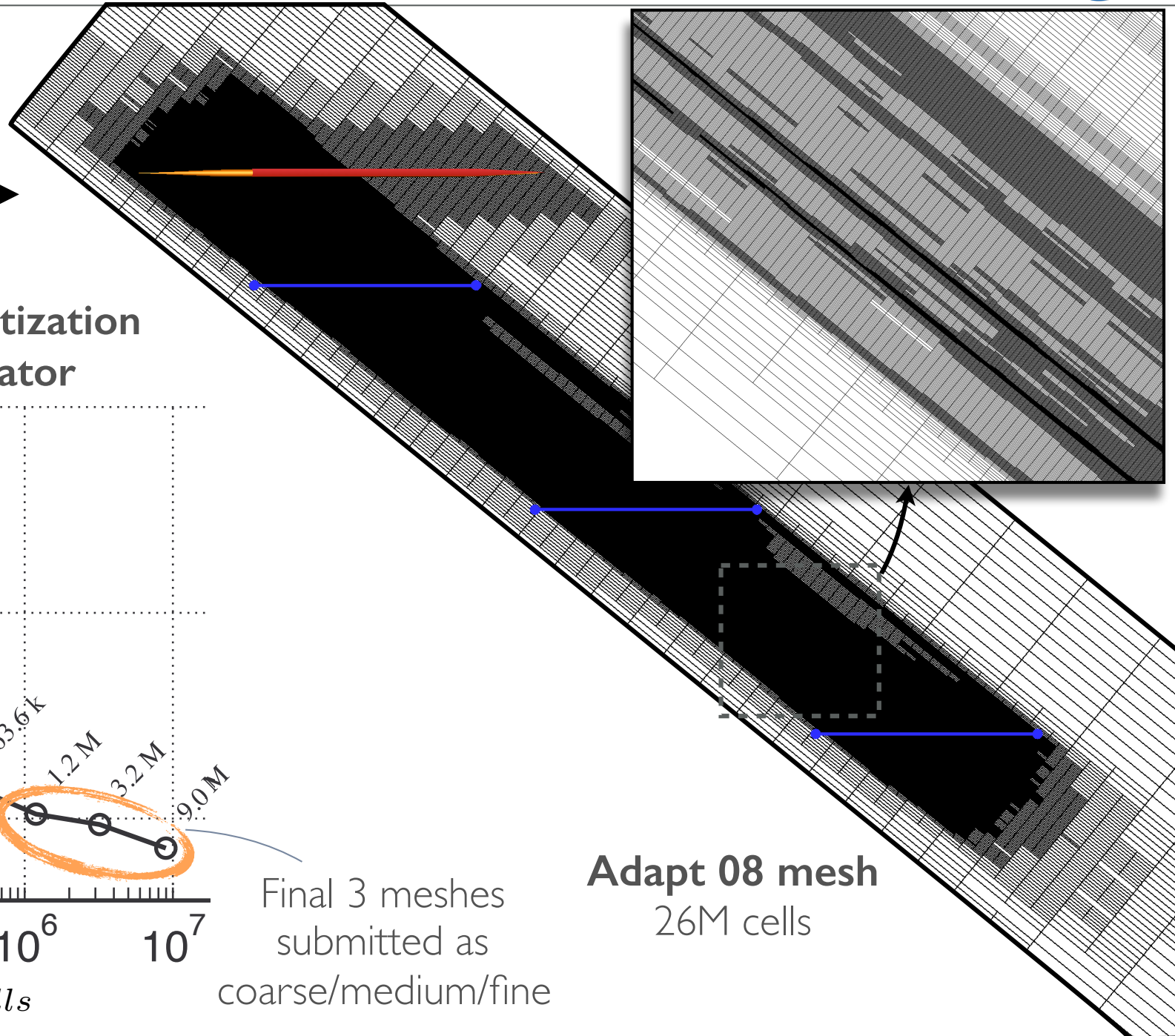
$$\alpha = 0^{\circ}$$

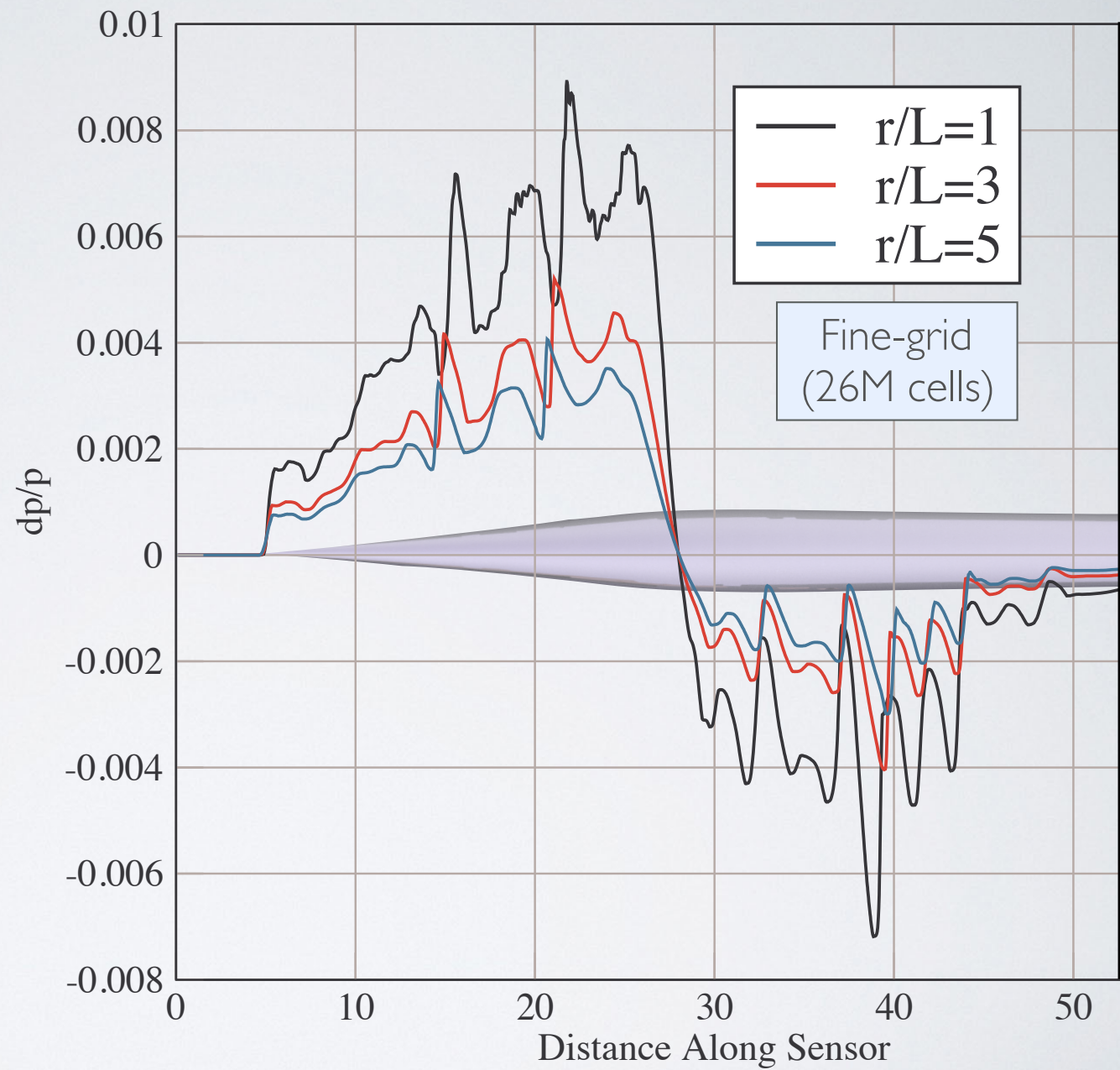
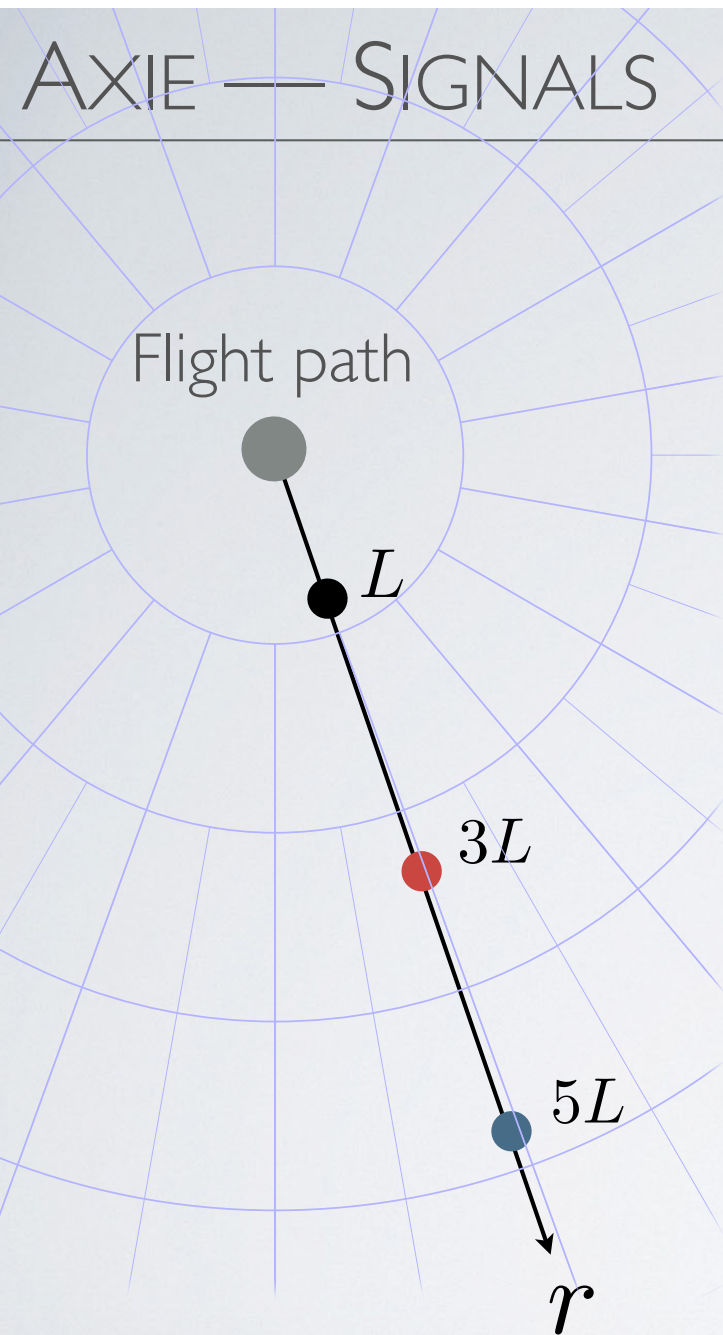
Adjoint Discretization Error Indicator



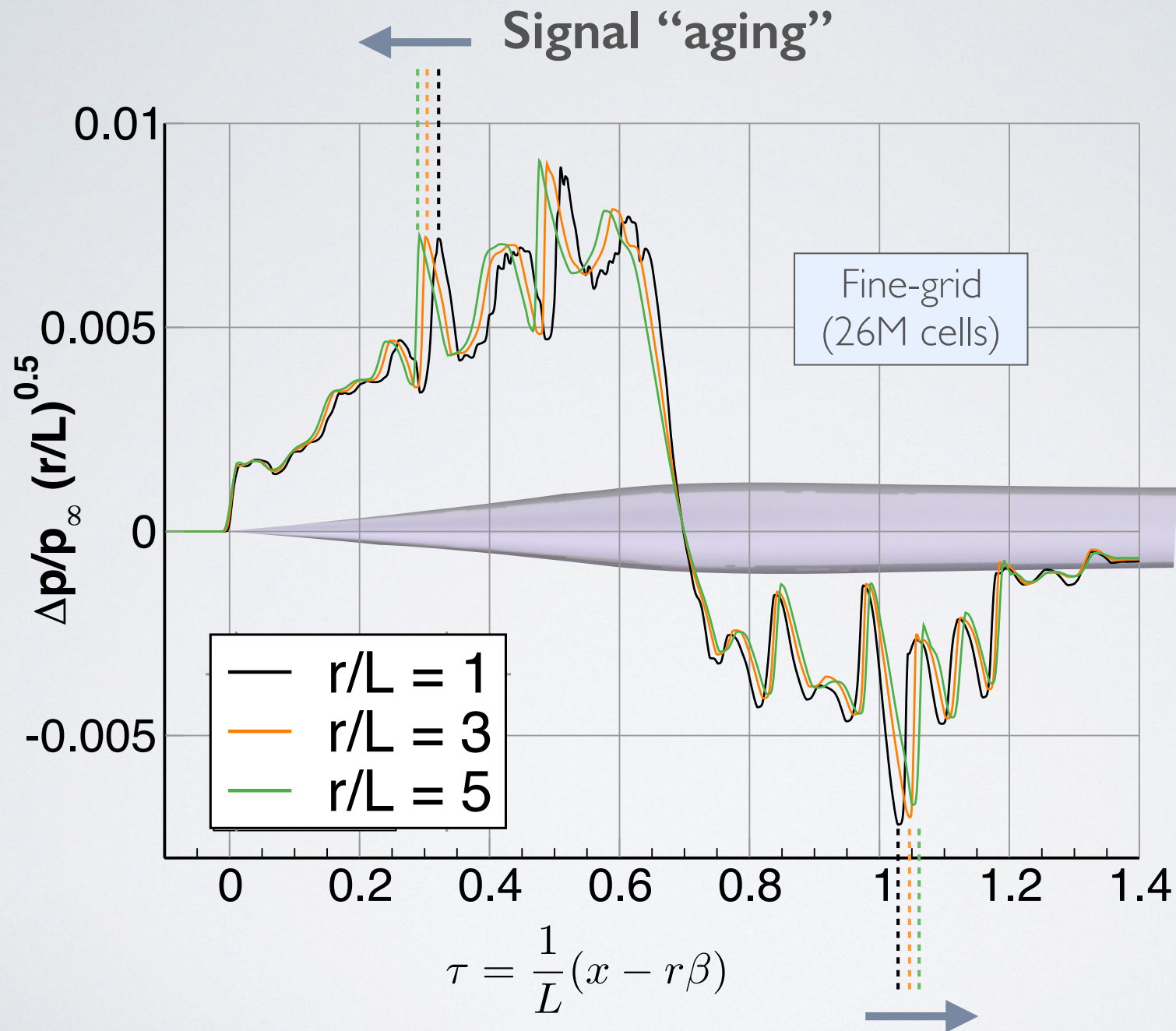
Final 3 meshes
submitted as
coarse/medium/fine

Adapt 08 mesh
26M cells

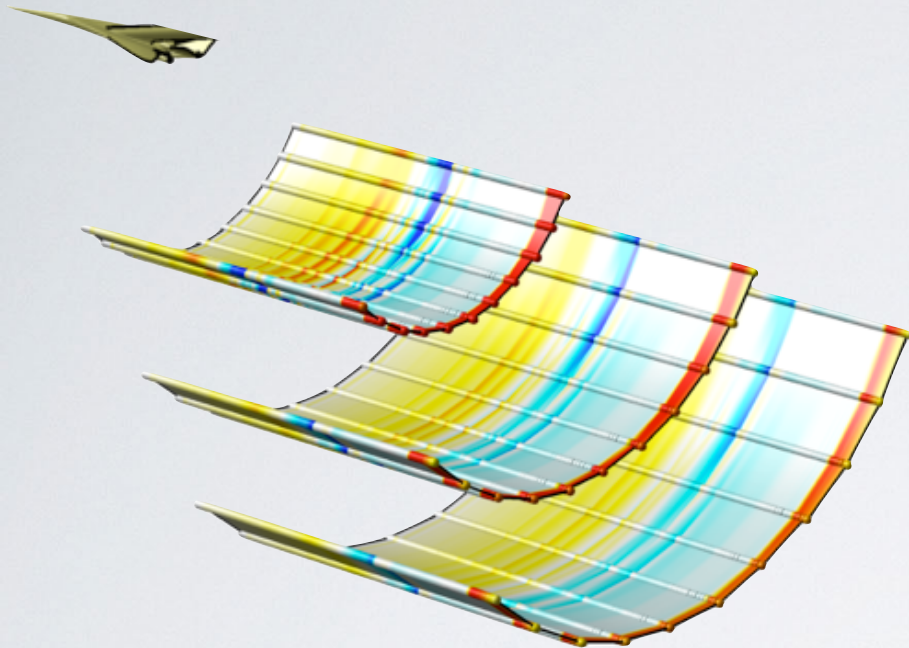




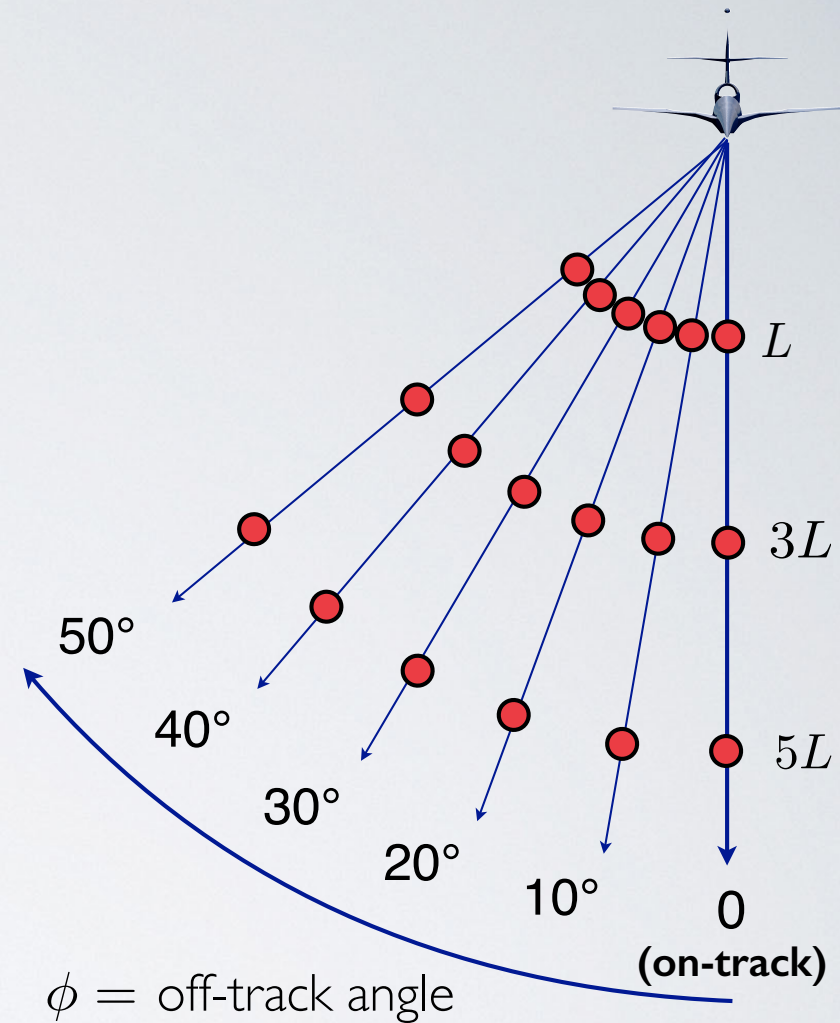
AXIE — SIGNALS



BOOM CARPETS

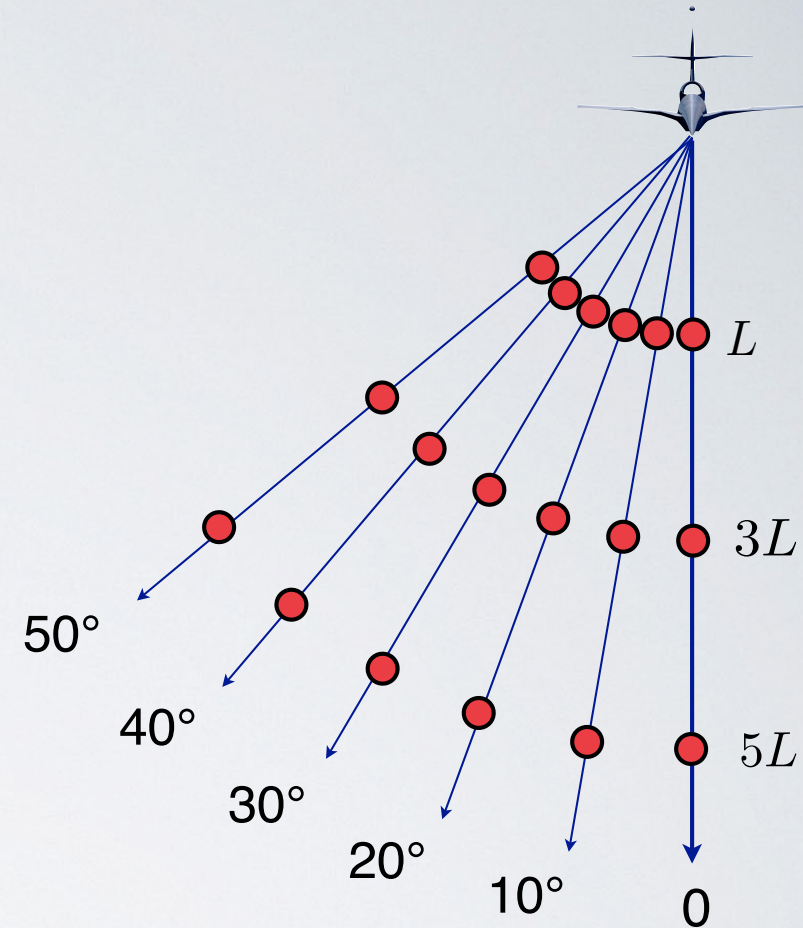
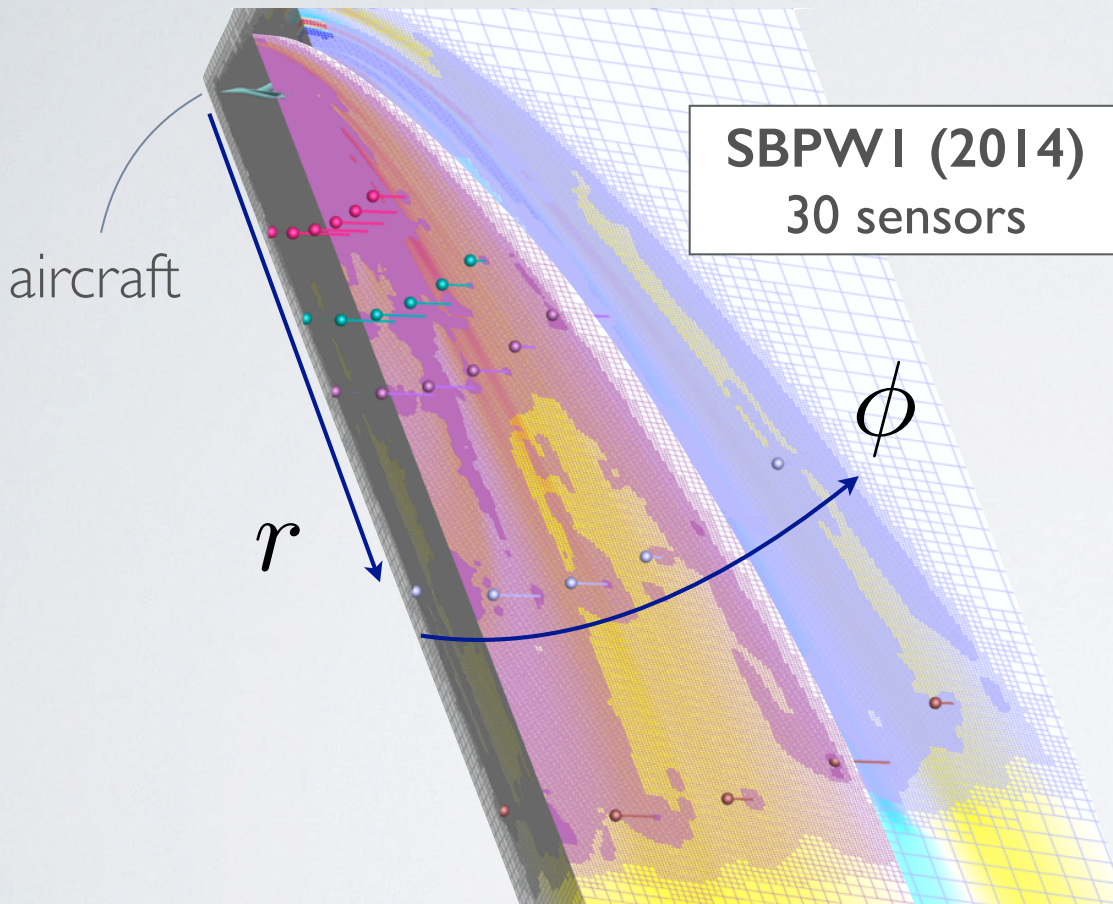


Boom Carpets



BOOM CARPETS WITH MONOLITHIC MESH

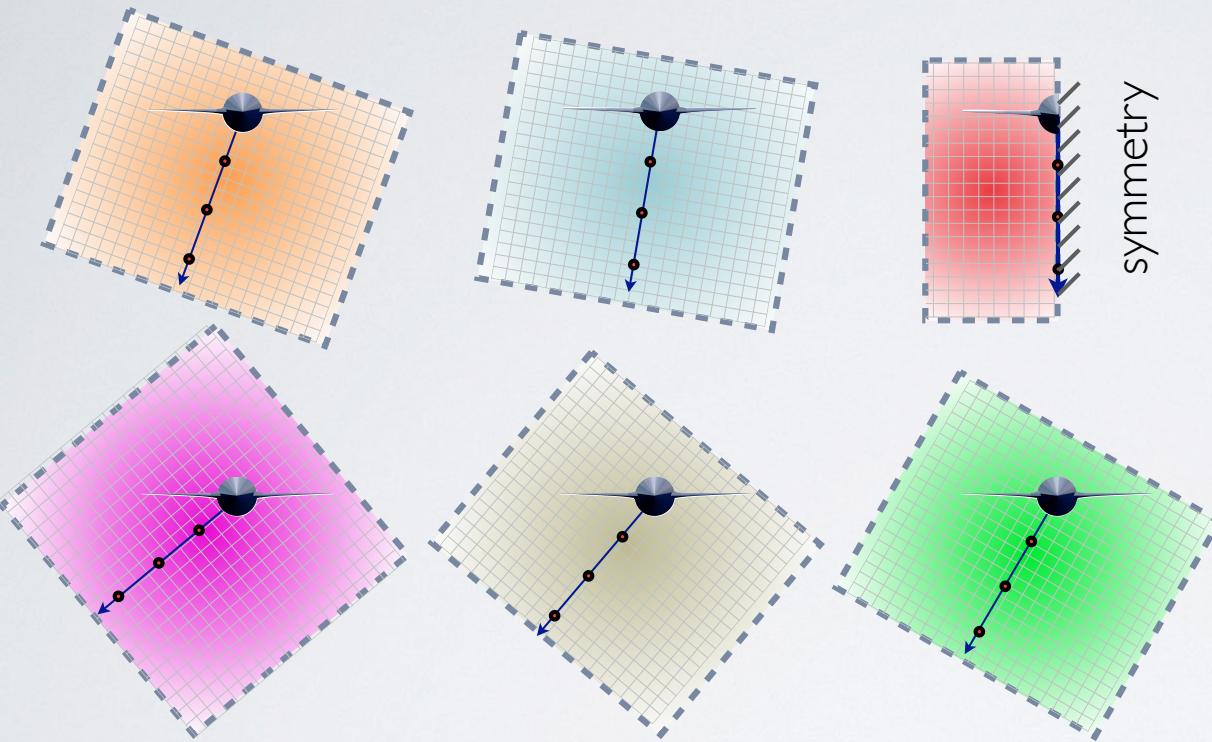
Compute entire carpet
in a single Cartesian mesh



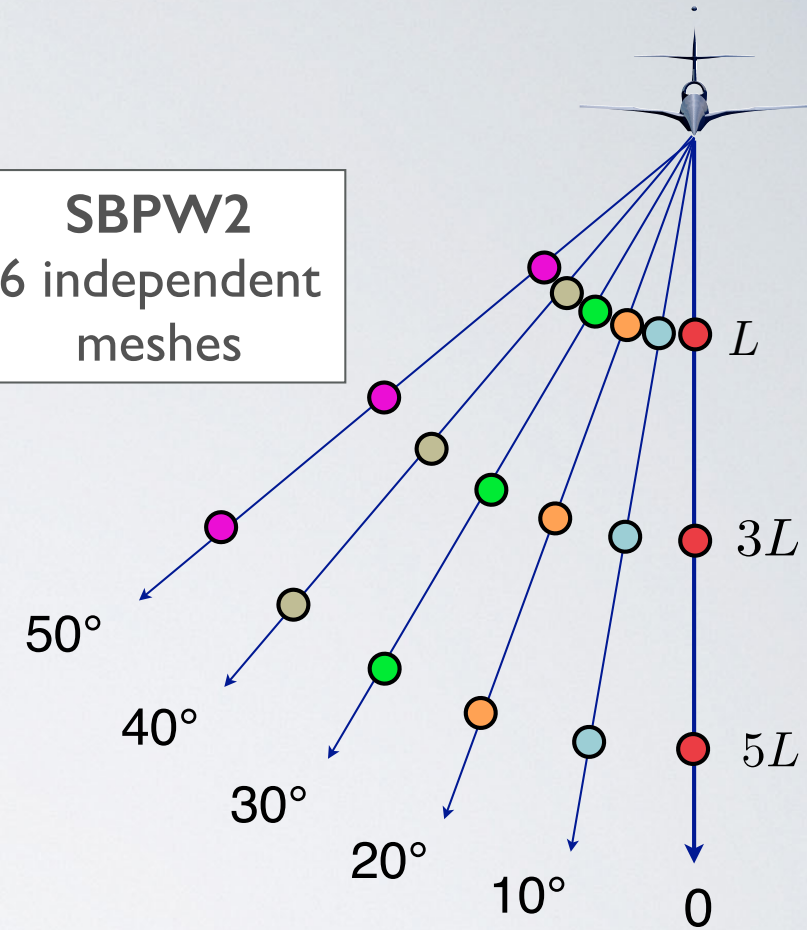
- ▶ Off-track angles are misaligned
 - ▶ Aspect ratio is constrained
- } **high cell-counts**

DECOMPOSING BOOM CARPETS

Use independent meshes
each rotated to off-track angle

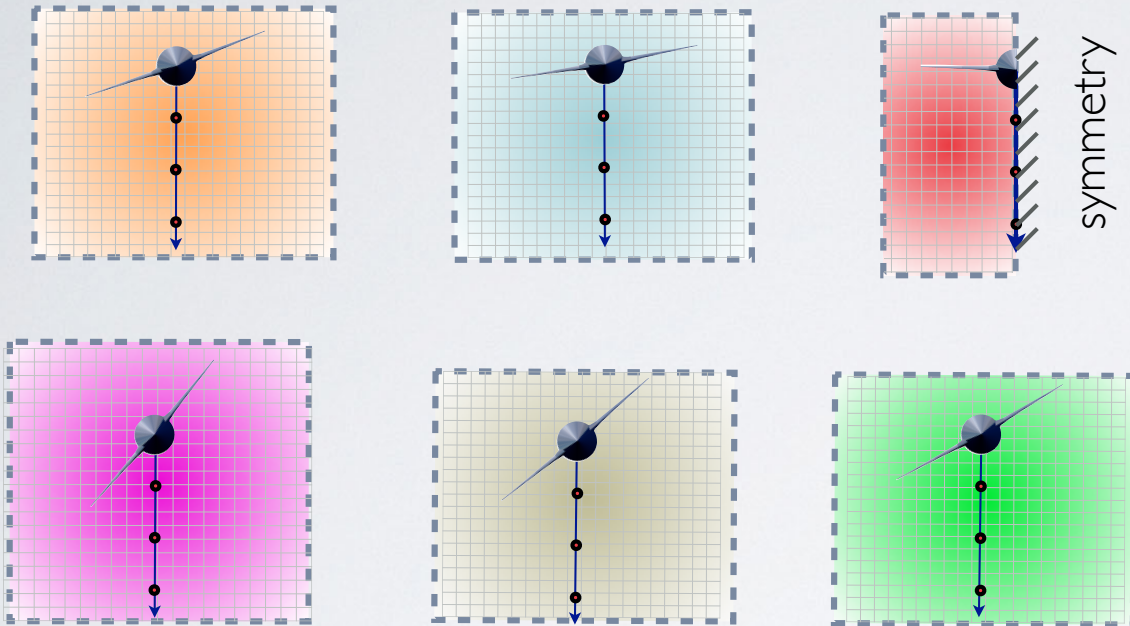


SBPW2
6 independent
meshes

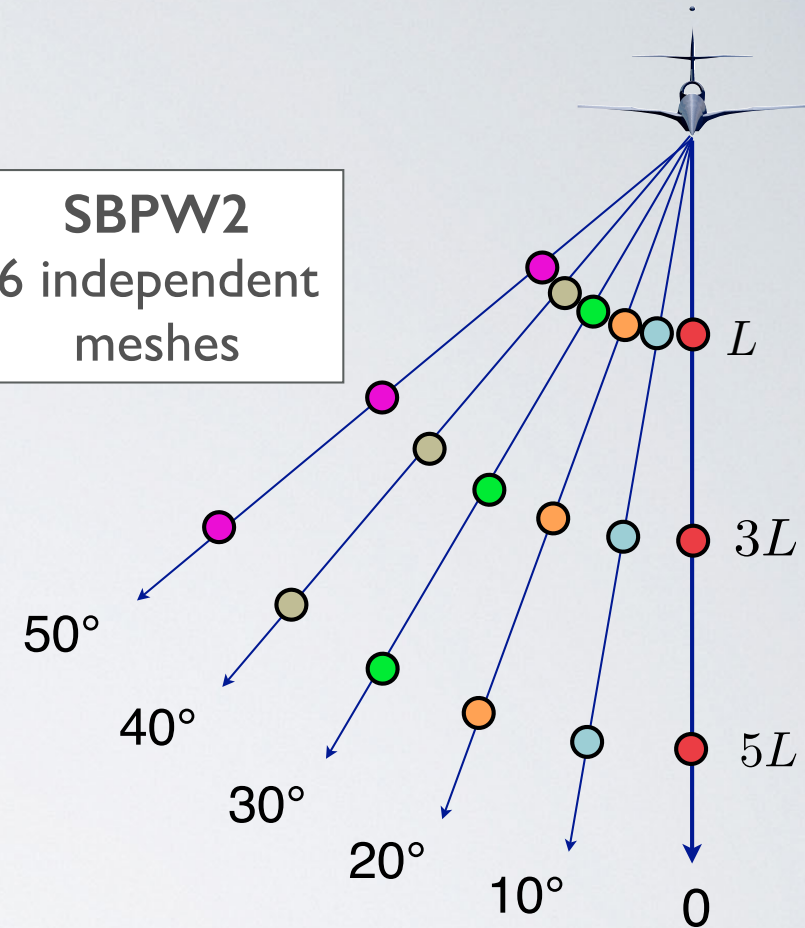


DECOMPOSING BOOM CARPETS

Use independent meshes
each rotated to off-track angle

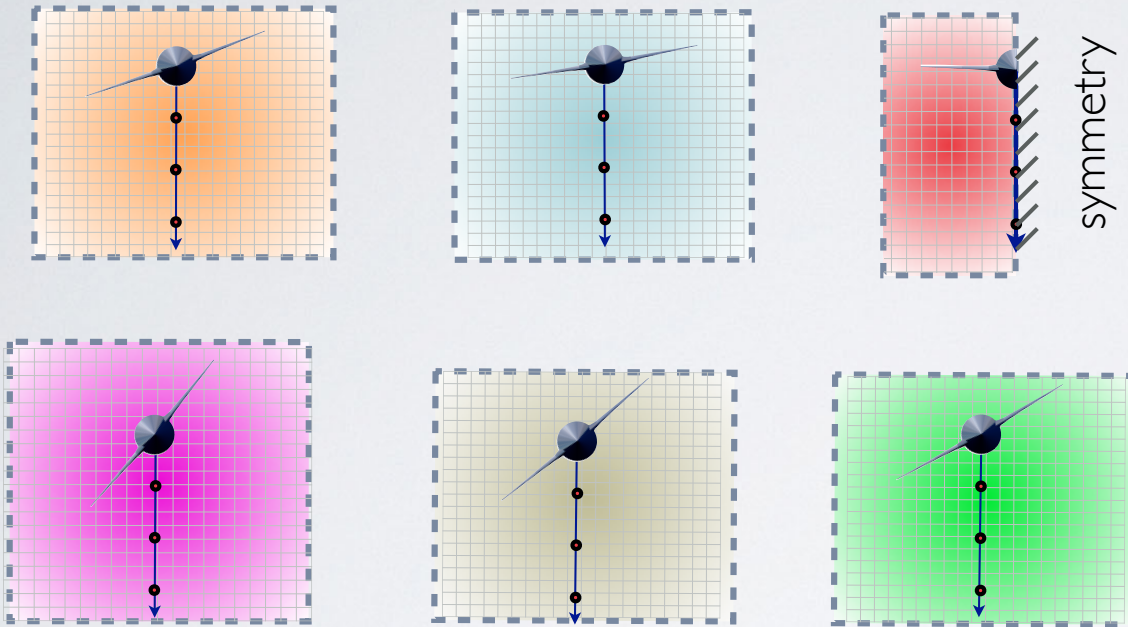


SBPW2
6 independent
meshes

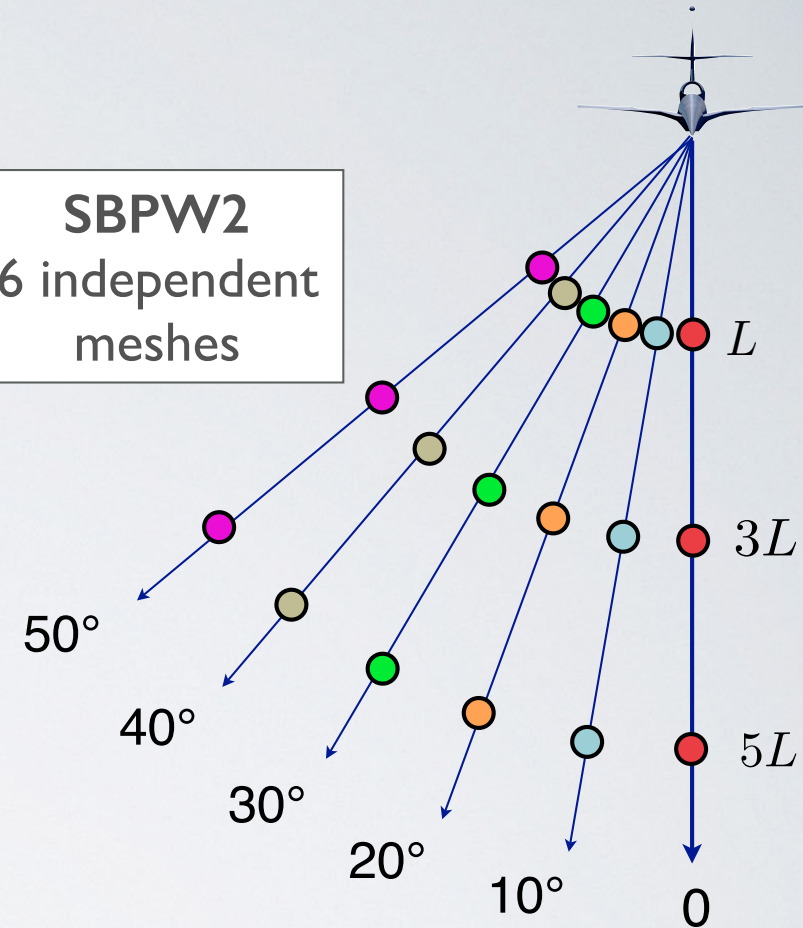


DECOMPOSING BOOM CARPETS

Use independent meshes
each rotated to off-track angle



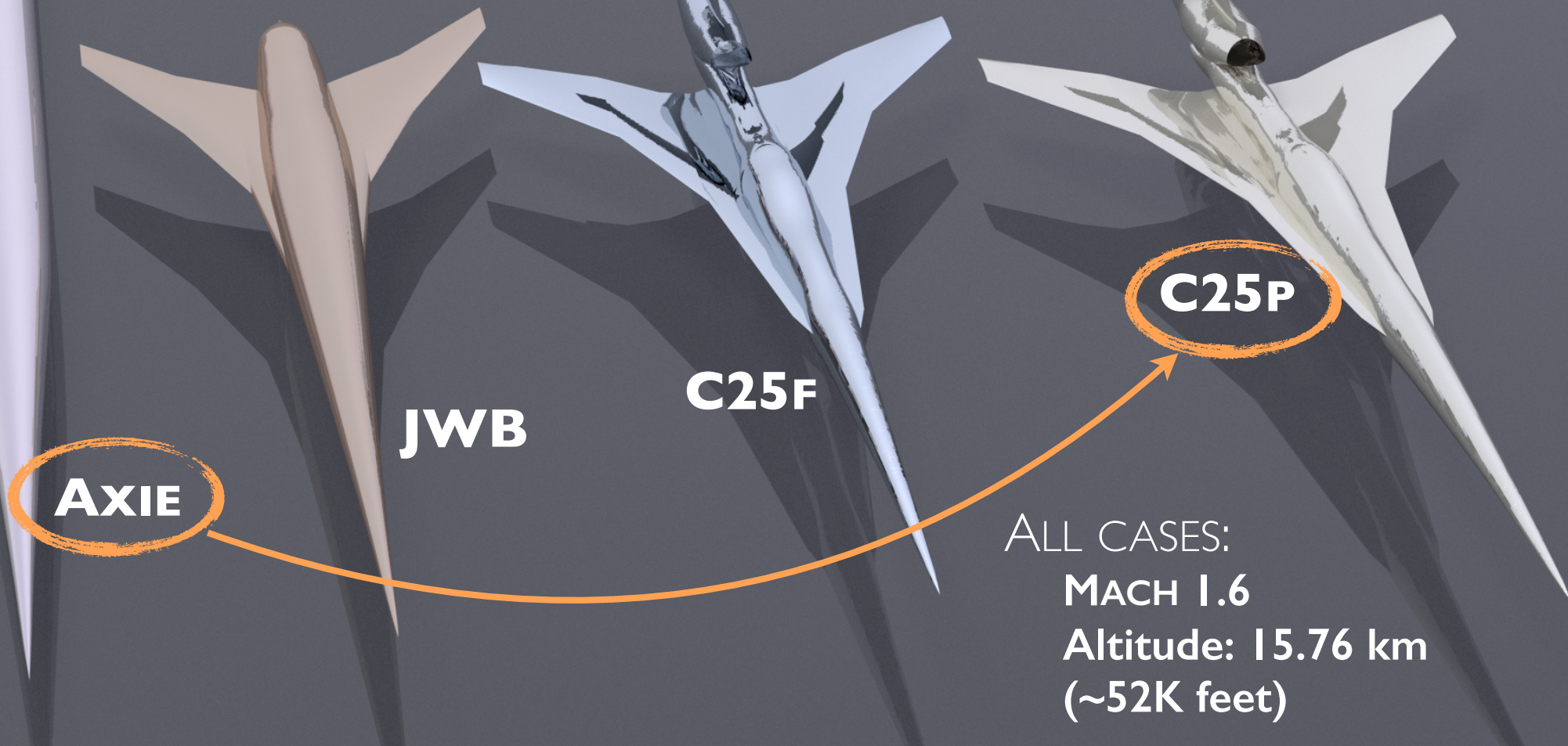
SBPW2
6 independent
meshes



Splitting permits

- ▶ **azimuthal alignment**, which permits:
 - ▶ higher **stretching**
- ▶ Simultaneous computation of off-track angles in carpet

NEARFIELD CASES



CONCEPT 25D

POWERED VARIANT (**C25P**)

Flight Conditions

Mach 1.6

$$\alpha = 3.375^\circ$$

Inlet Conditions

$$\frac{p}{p_\infty} = 3.26$$

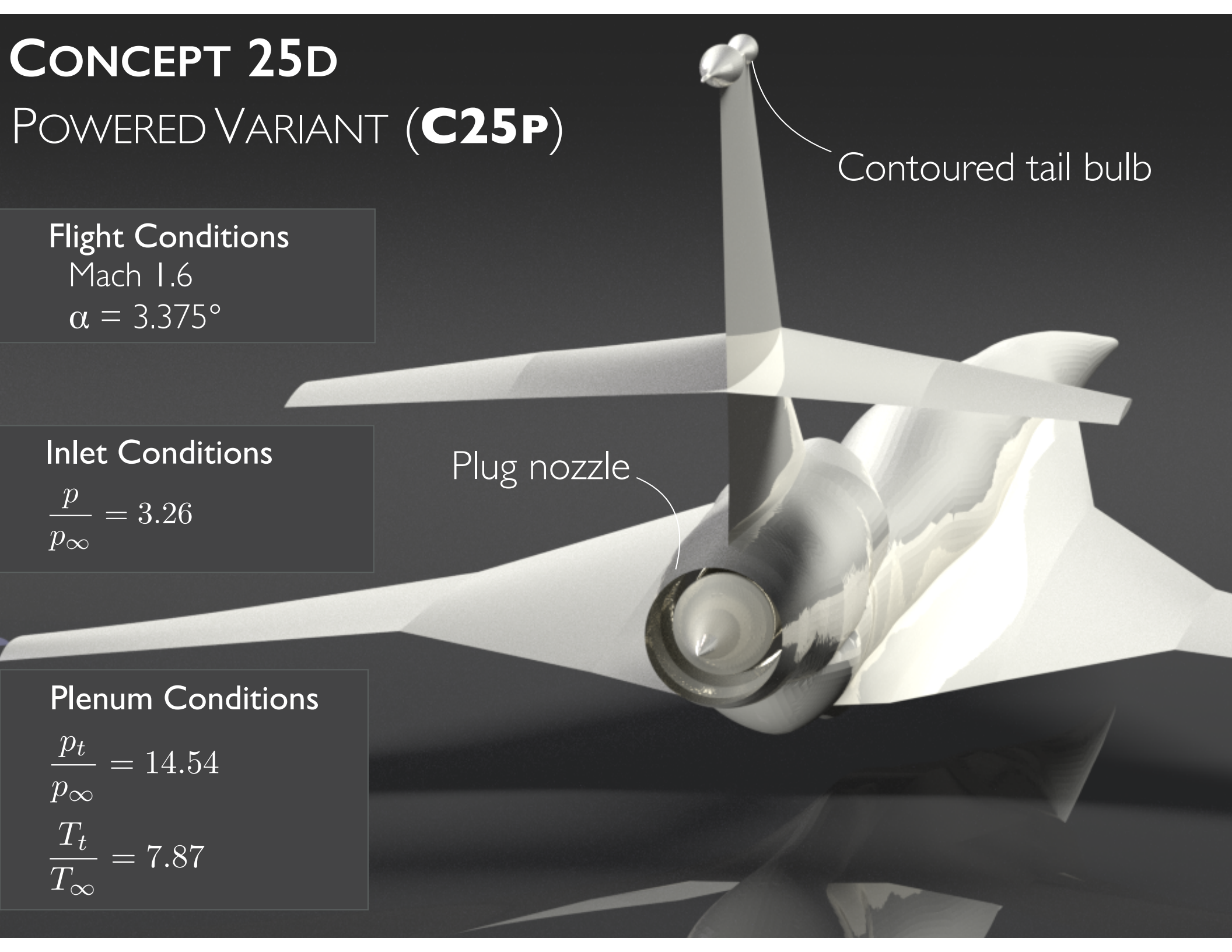
Plenum Conditions

$$\frac{p_t}{p_\infty} = 14.54$$

$$\frac{T_t}{T_\infty} = 7.87$$

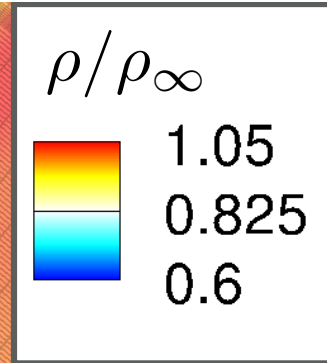
Contoured tail bulb

Plug nozzle

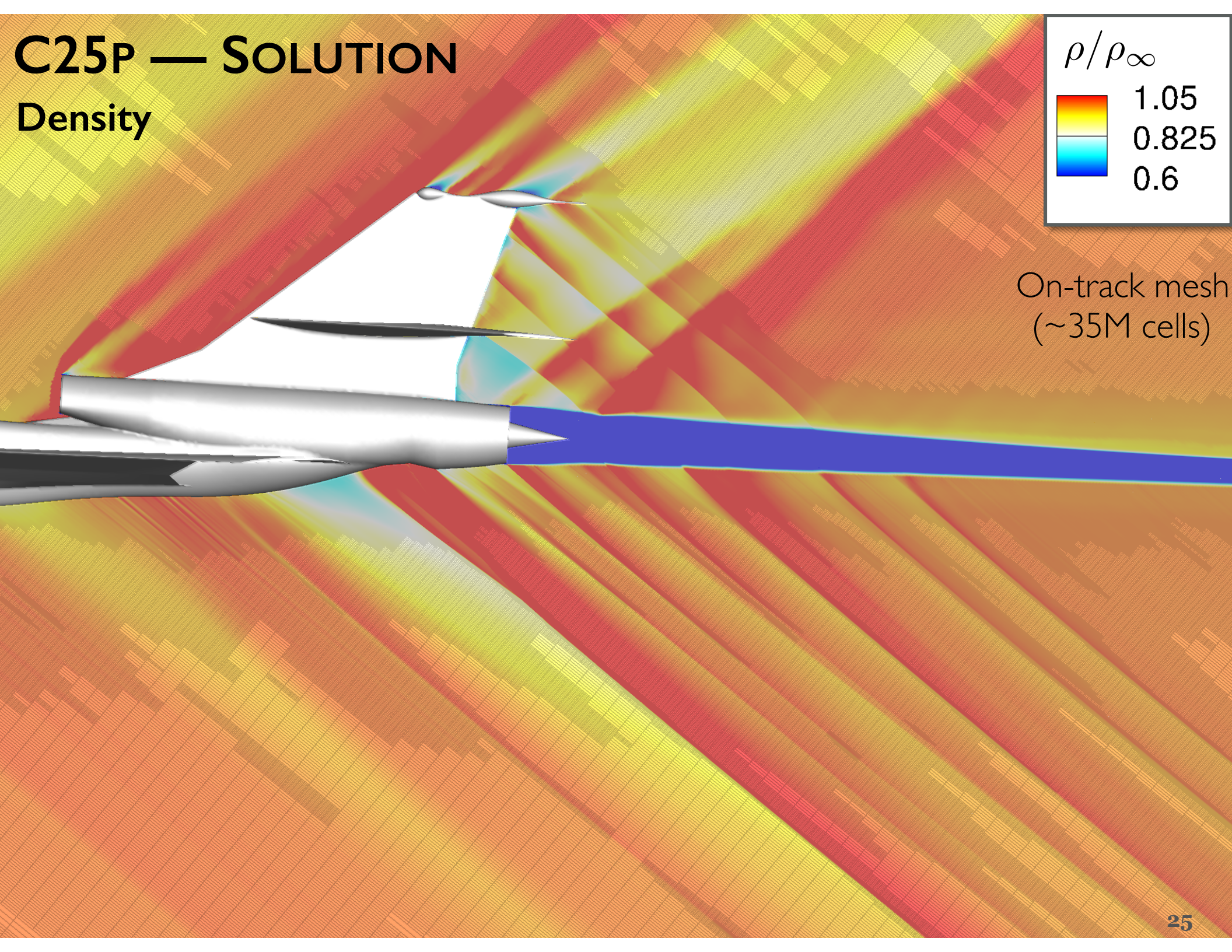


C25P — SOLUTION

Density

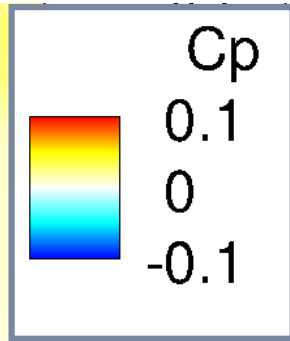


On-track mesh
(~35M cells)

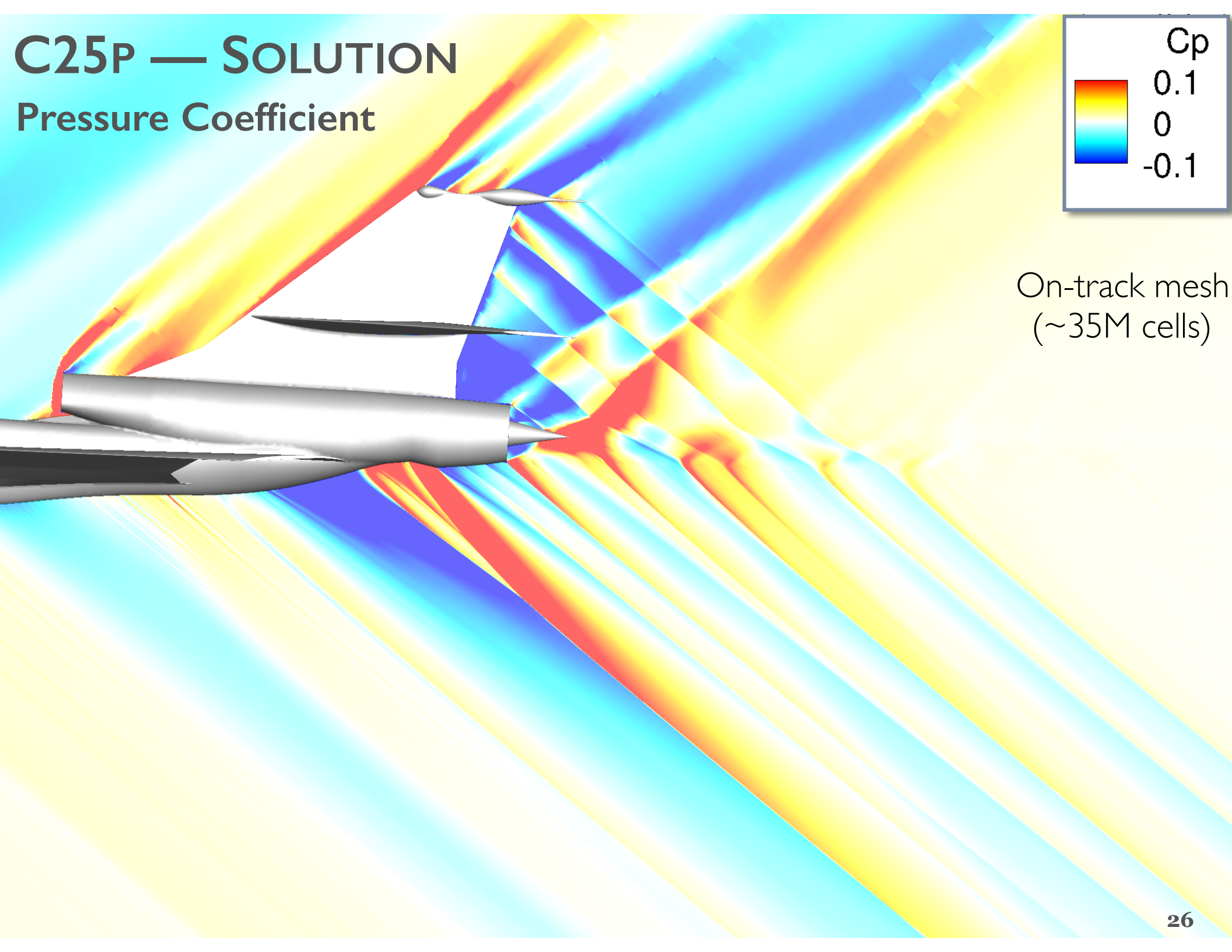


C25P — SOLUTION

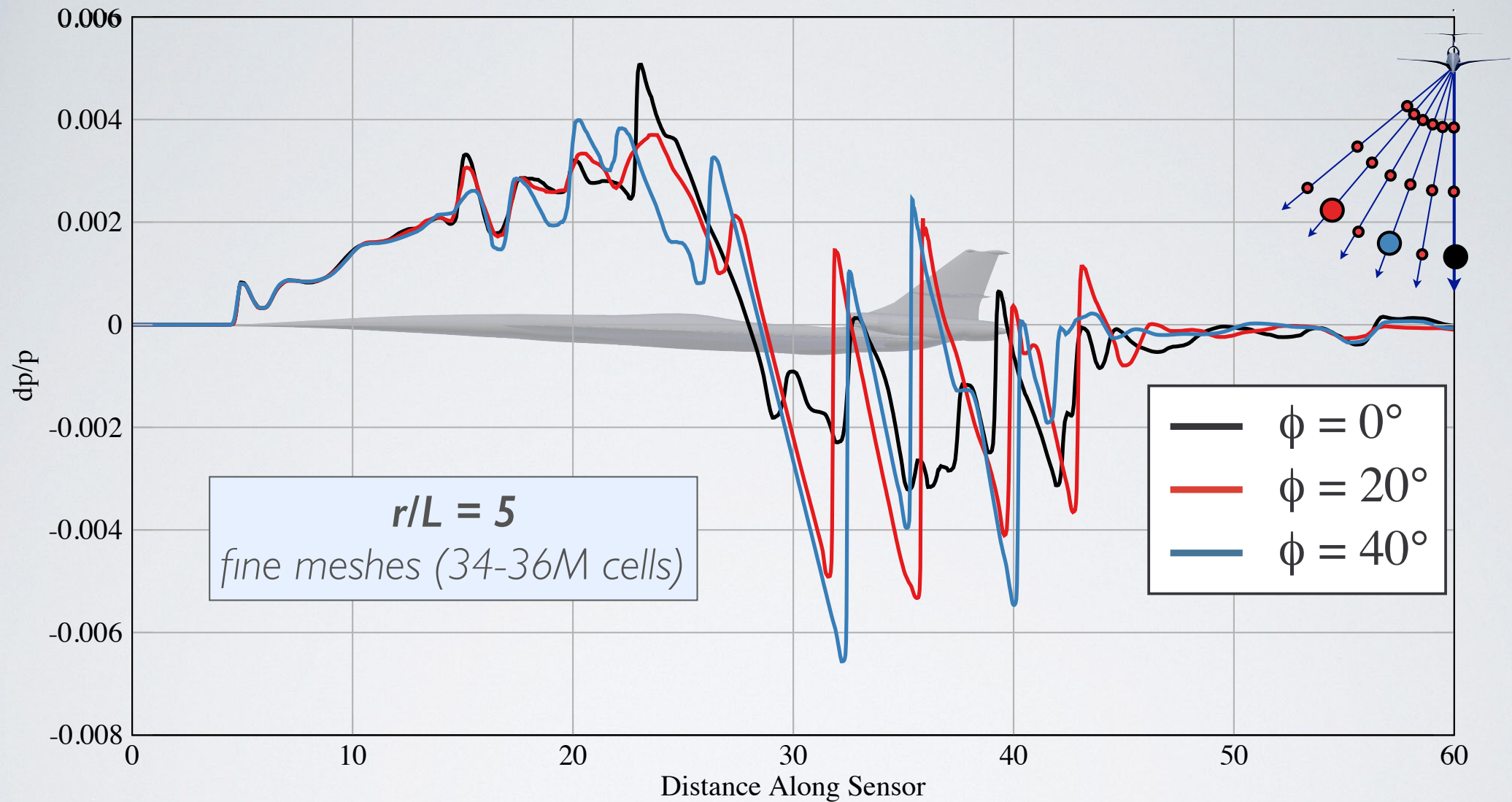
Pressure Coefficient



On-track mesh
(~35M cells)



C25P — SIGNATURES



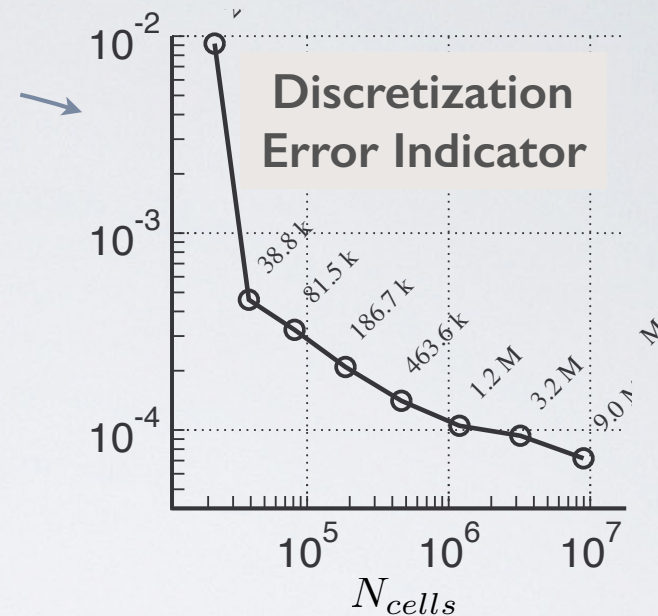
Each off-track angle — 35M cell mesh: 4hr 30min on 28 cores
Includes flow solution + all meshing, adjoint solutions, error estimation, etc.

ASSESSING MESH CONVERGENCE

Adjoint: Is the integrated functional converging asymptotically?

- Non-intuitive units on error

$$\mathcal{J}_r = \int_0^L w(\ell) \left(\frac{p(\ell) - p_\infty}{p_\infty} \right)^2 d\ell$$

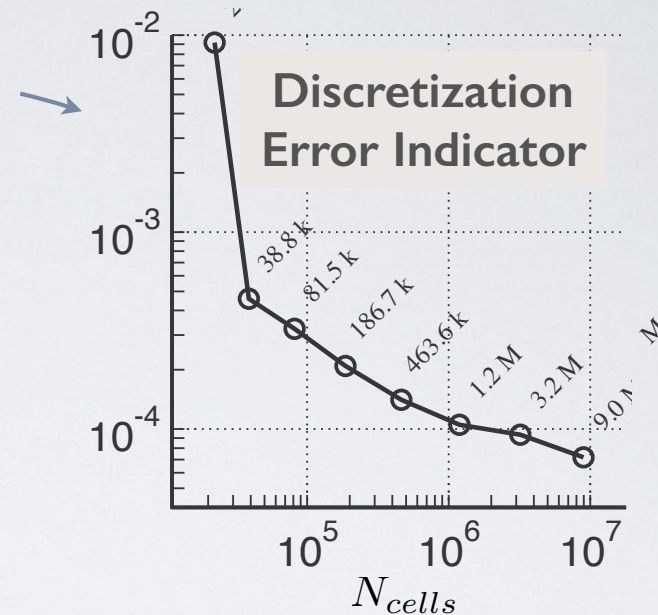


ASSESSING MESH CONVERGENCE

Adjoint: Is the integrated functional converging asymptotically?

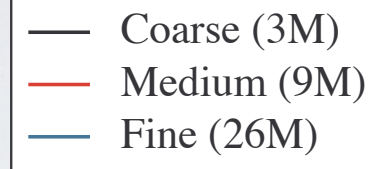
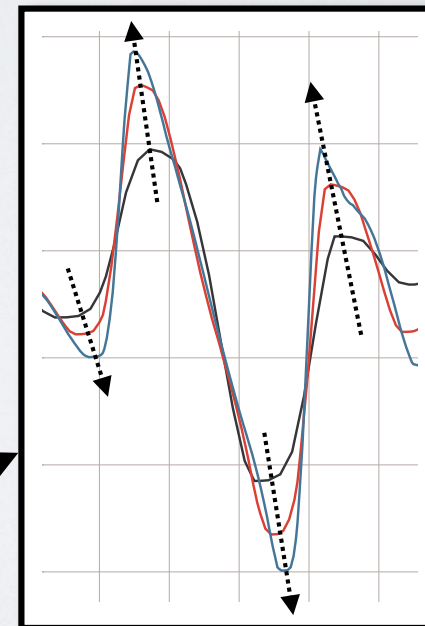
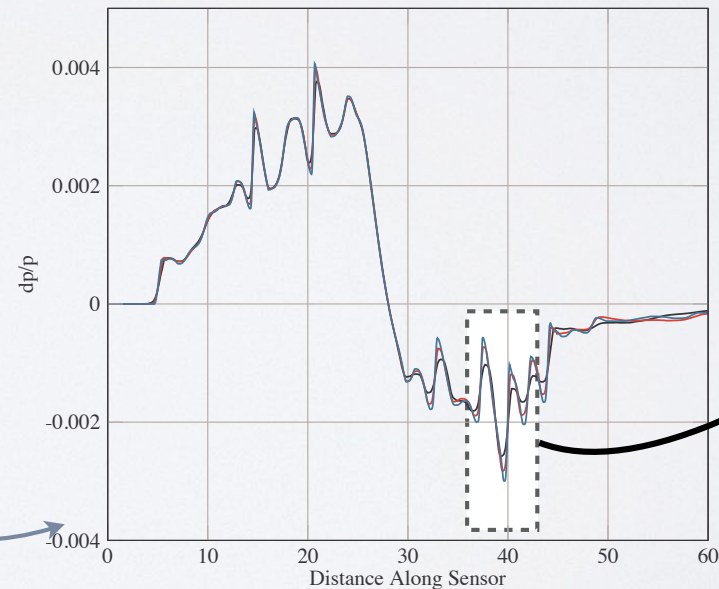
- ▶ Non-intuitive units on error

$$\mathcal{J}_r = \int_0^L w(\ell) \left(\frac{p(\ell) - p_\infty}{p_\infty} \right)^2 d\ell$$

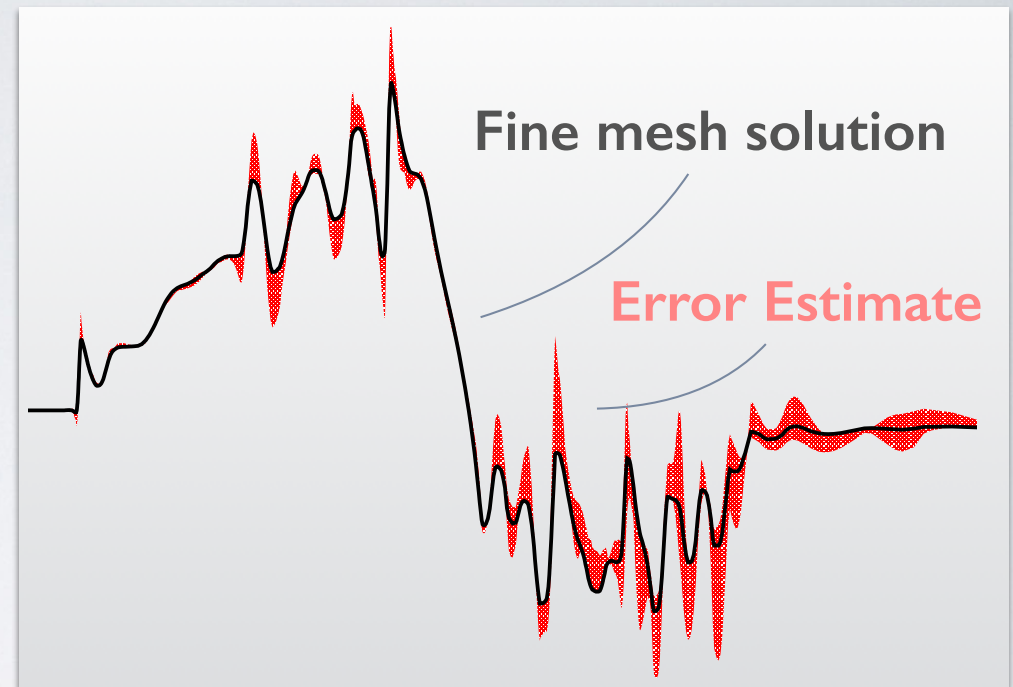
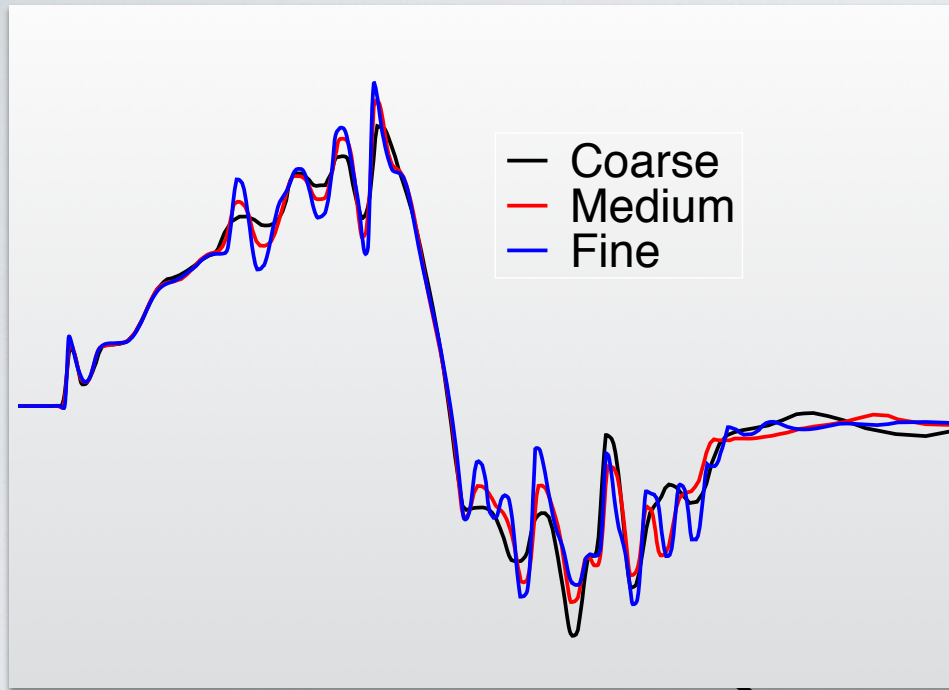


Qualitative: Are signal features converging with mesh refinement?

- ▶ Out of context, has no quantitative anchor, however:
- ▶ The signatures are the result of an error reducing process.



LOCAL ERROR ANALYSIS



Local Richardson extrapolation

- ▶ Incorporates estimate of global rate of convergence
- ▶ Reveals significant **local** variation in error and rate of convergence
- ▶ Can be used for any mesh refinement technique (not just adjoint-based)

Details: ***AIAA Paper 2017-3255***

Figure 10. AXIE signature computed on fine grids plotted with discretization error estimates ($R = 5$).

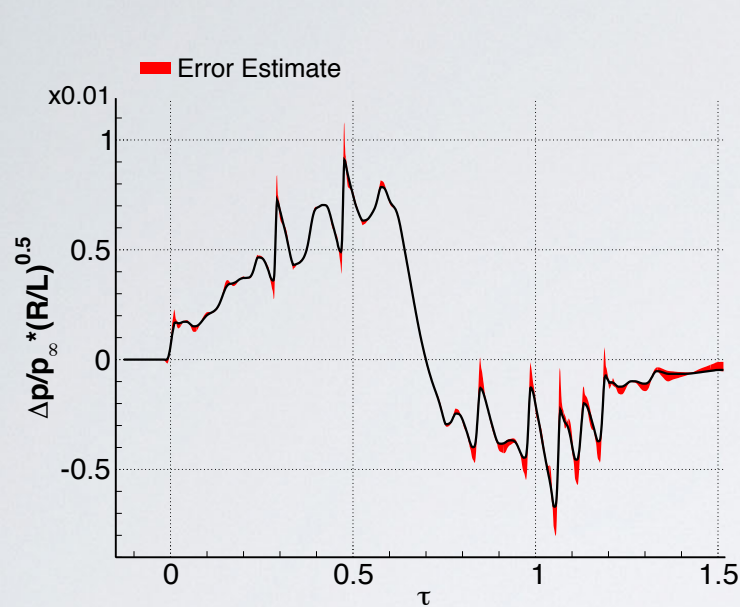


a) AA, CA, CC, FA (shown), GA, HA, IA, JA.

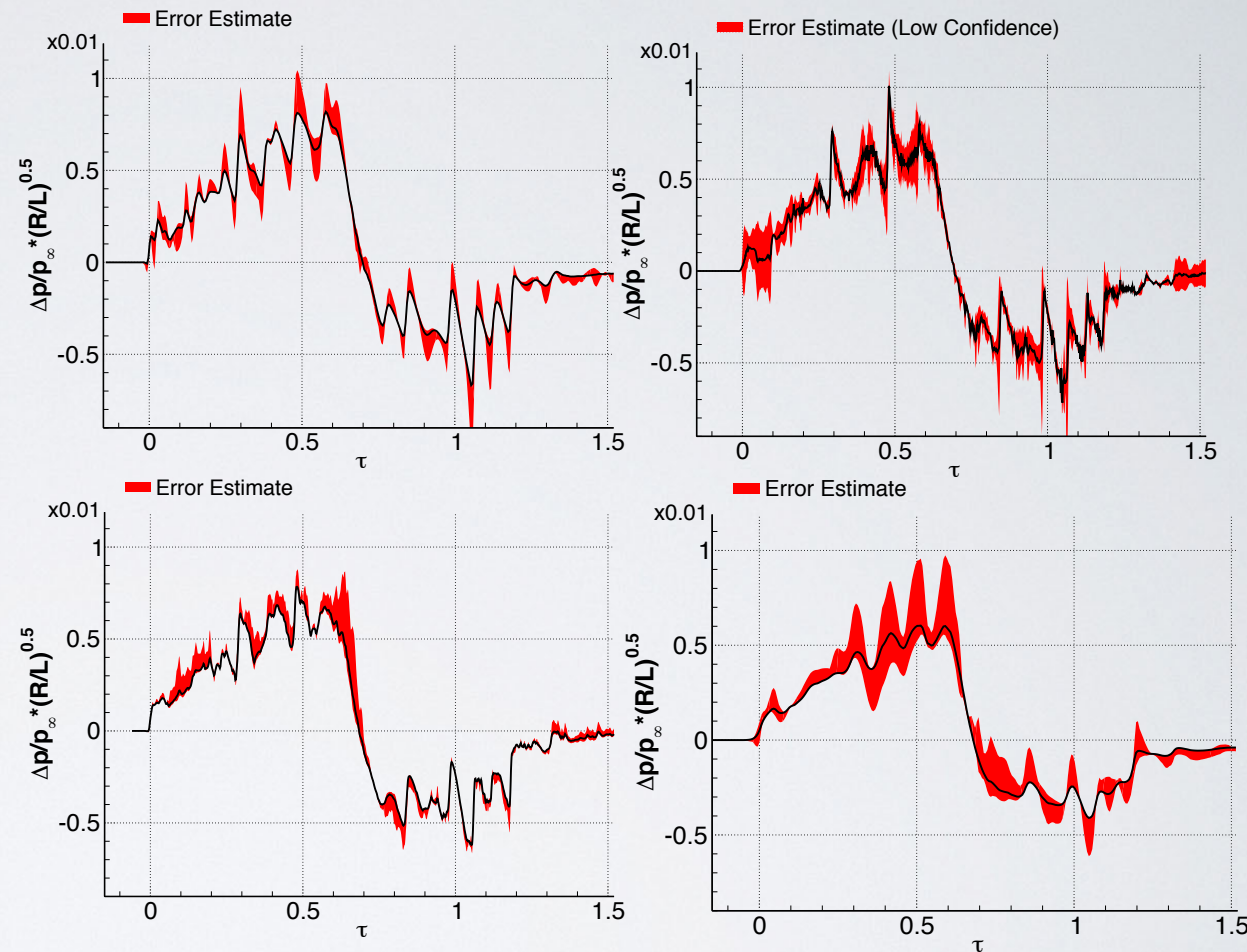
Good convergence
everywhere, tight bounds
[8 participants]

(2017) Park and Nemec, “Nearfield Summary and Statistical Analysis of the Second AIAA Sonic Boom Prediction Workshop”

Figure 10. AXIE signature computed on fine grids plotted with discretization error estimates ($R = 5$).



a) AA, CA, CC, FA (shown), GA, HA, IA, JA.



Good convergence
everywhere, tight bounds
[8 participants]

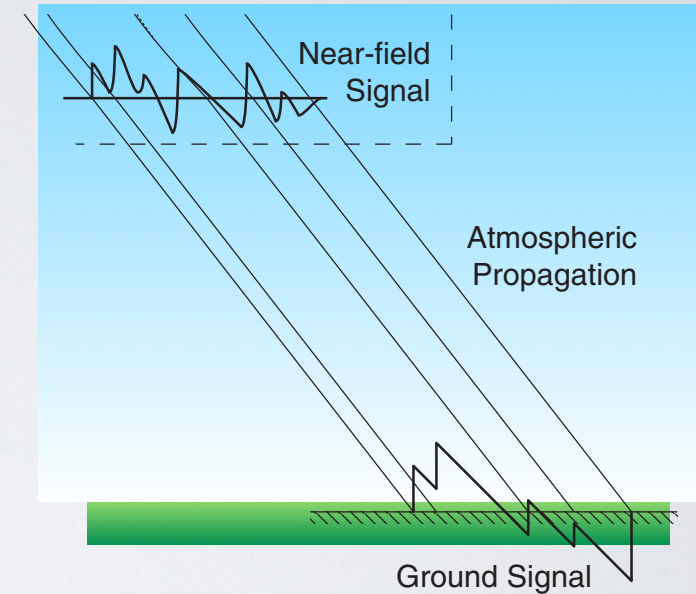
*Individual poorly
converged results*

(2017) Park and Nemec, “Nearfield Summary and Statistical Analysis of the Second AIAA Sonic Boom Prediction Workshop”

✓ Nearfield Workshop

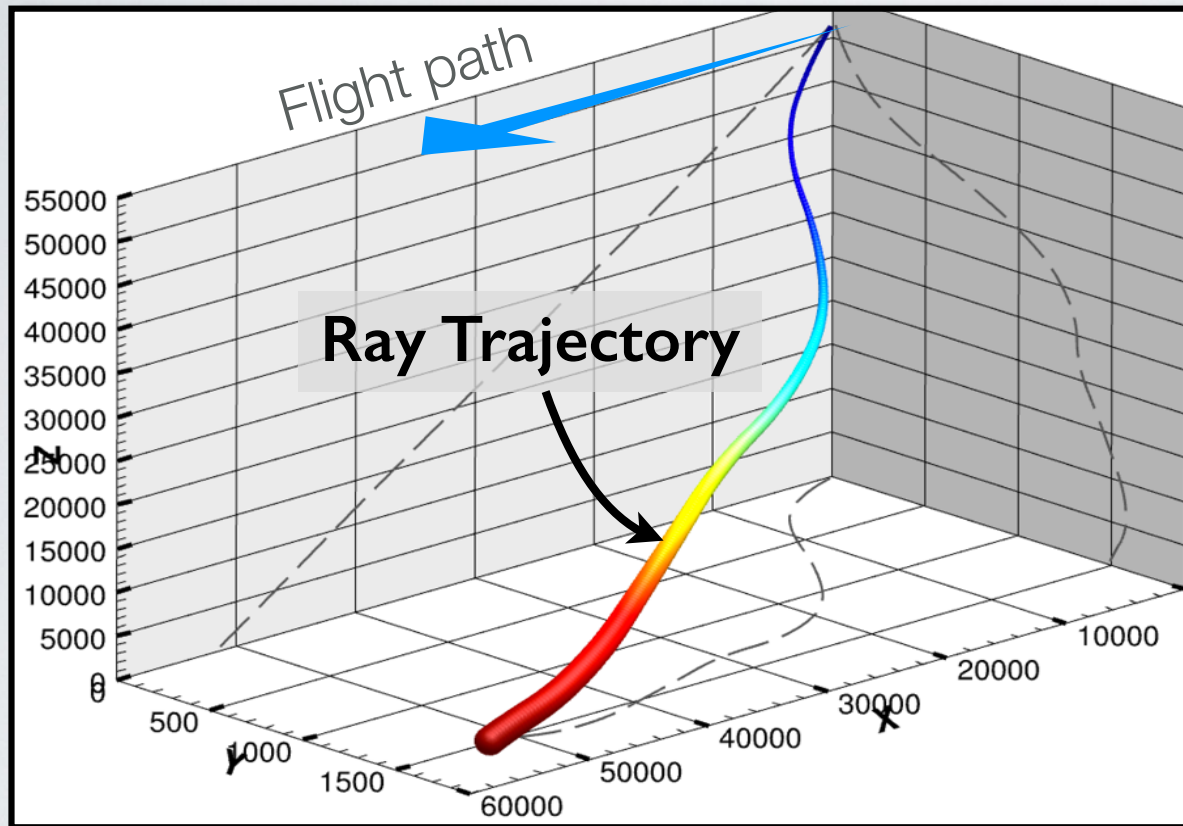
► Propagation Workshop — sBOOM

- Numerical approach
- Propagation Results
- Full Vehicle-to-Boom Simulation Path
- Conclusions



sBOOM

1. Ray-tracing
2. Quasi-1D, augmented Burgers' equation

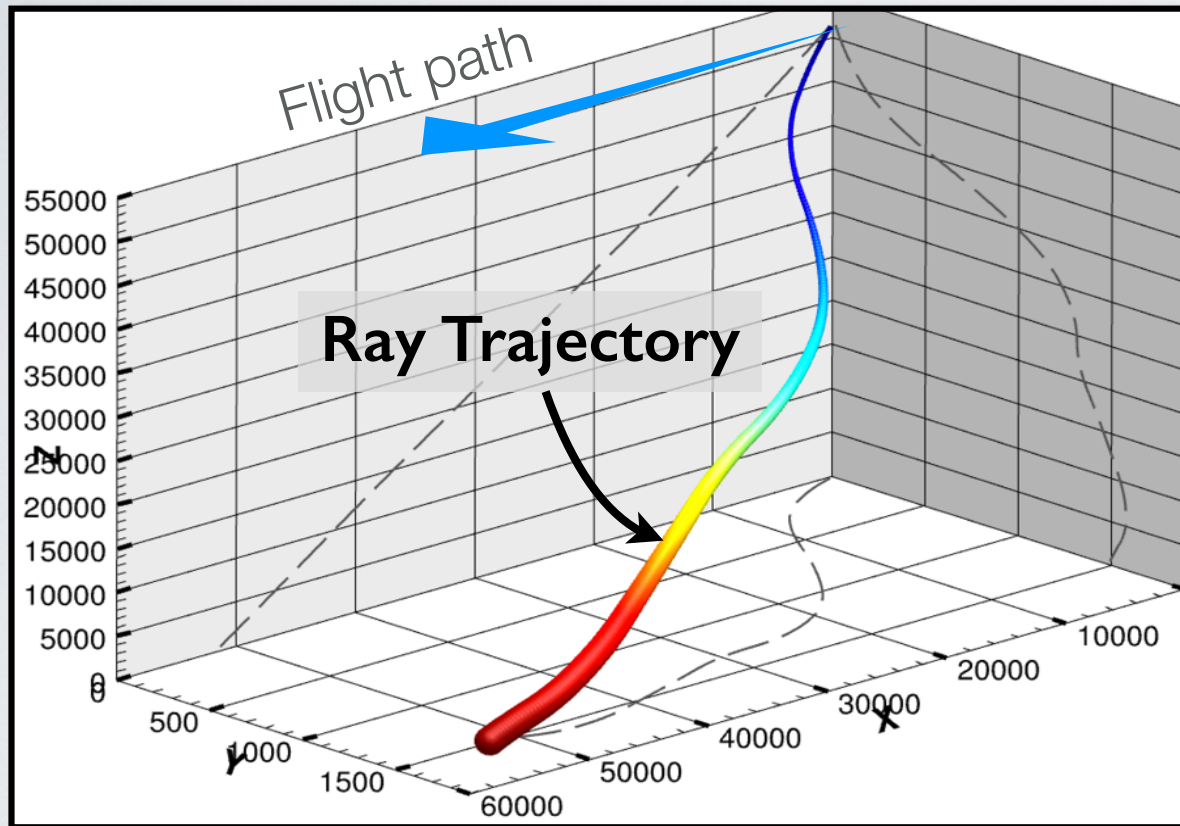


(2011) Rallabhandi, *“Advanced Sonic Boom Prediction Using the Augmented Burgers Equation”*

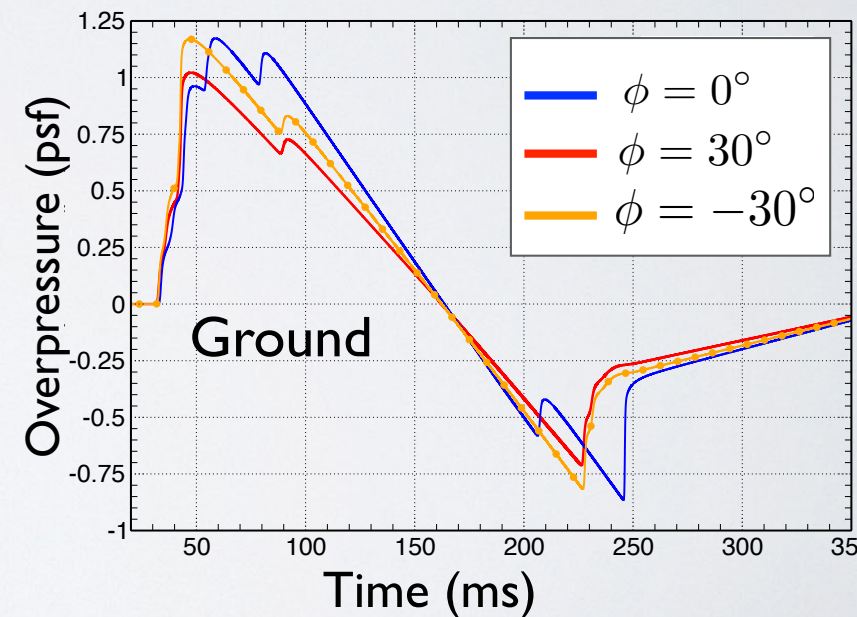
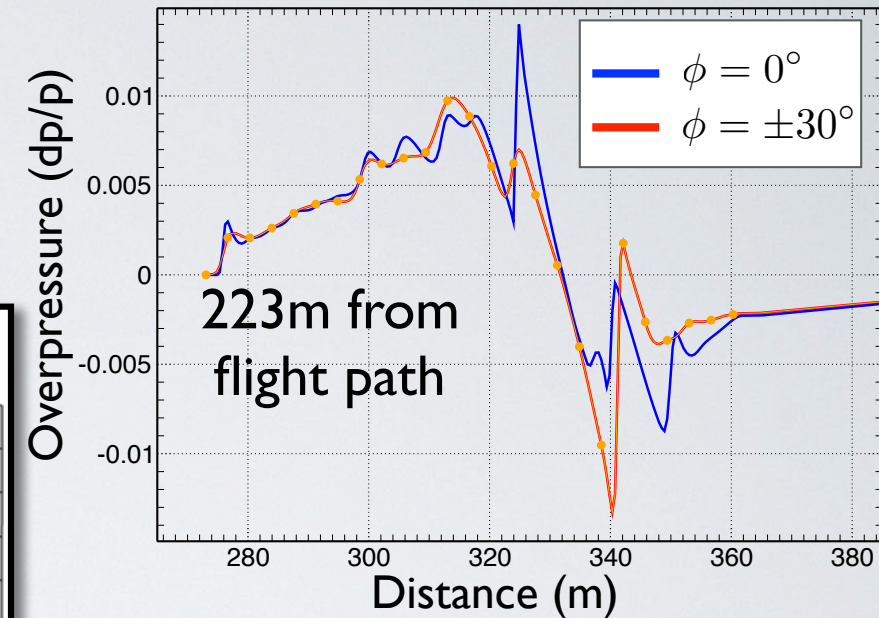
ATMOSPHERIC PROPAGATION WITH sBOOM

sBOOM

1. Ray-tracing
2. Quasi-1D, augmented Burgers' equation



(2011) Rallabhandi, "Advanced Sonic Boom Prediction Using the Augmented Burgers Equation"



ATMOSPHERIC PROPAGATION WITH sBOOM

► Discretization error

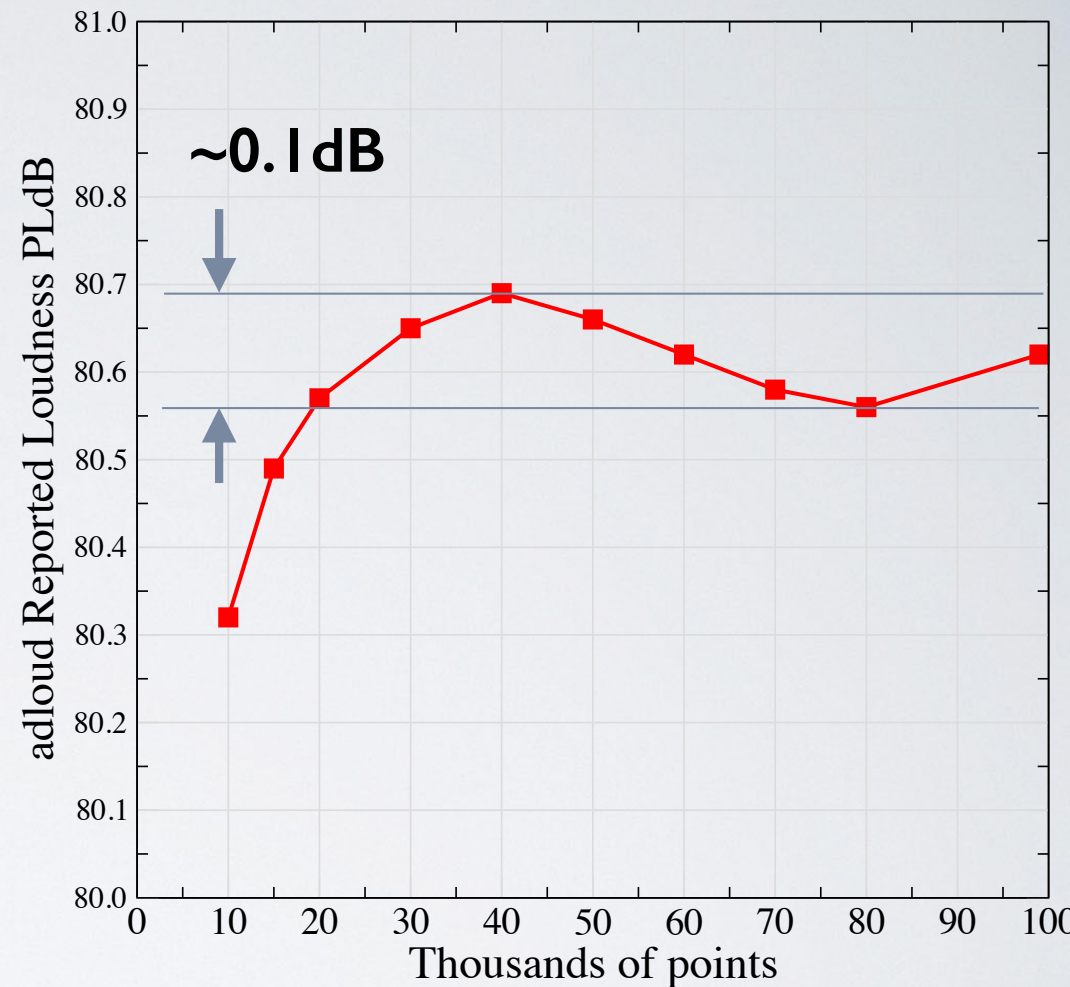
Finite difference solution of PDE on uniform grid

► Input error

Input $\sim 100\times$ coarser than output
Oversampling introduces high freq.

► Mesh refinement studies

Numerical sources of error **~ 0.1 dB**
(*cf. atmospheric variability of ~ 5 dB*)
But not clearly asymptotic



PROPAGATION CASES



AXIE

$L_{ref} = 43\text{m (141 ft)}$

Conditions:

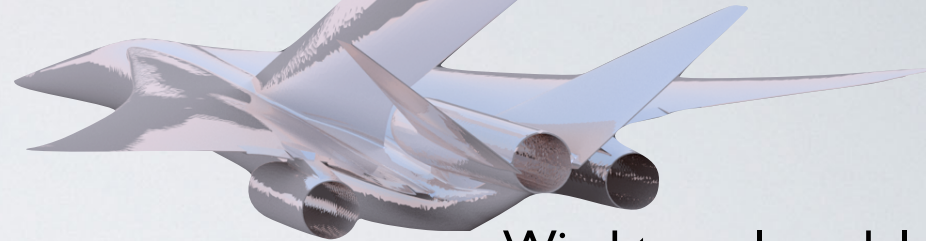
$$M_{\infty} = 1.6$$

Altitude = 15.8 km (~52K ft)

Profiles:

- ISO Standard Atmosphere
- ISO Std. Atm. with 70% humidity
- Hot day, coastal Virginia
- Hot dry day, Edwards AFB

LM-102I



Wind tunnel model
from SBPWI (2014)

Conditions:

$$M_{\infty} = 1.6$$

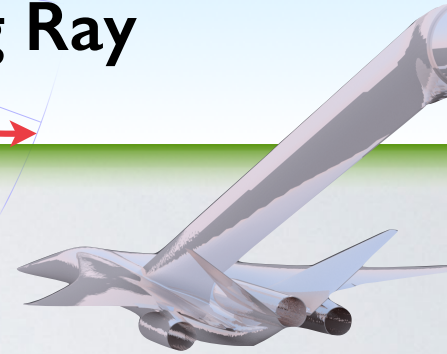
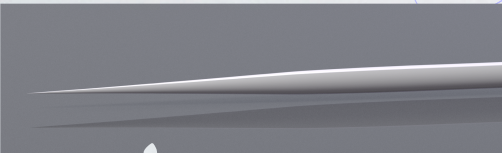
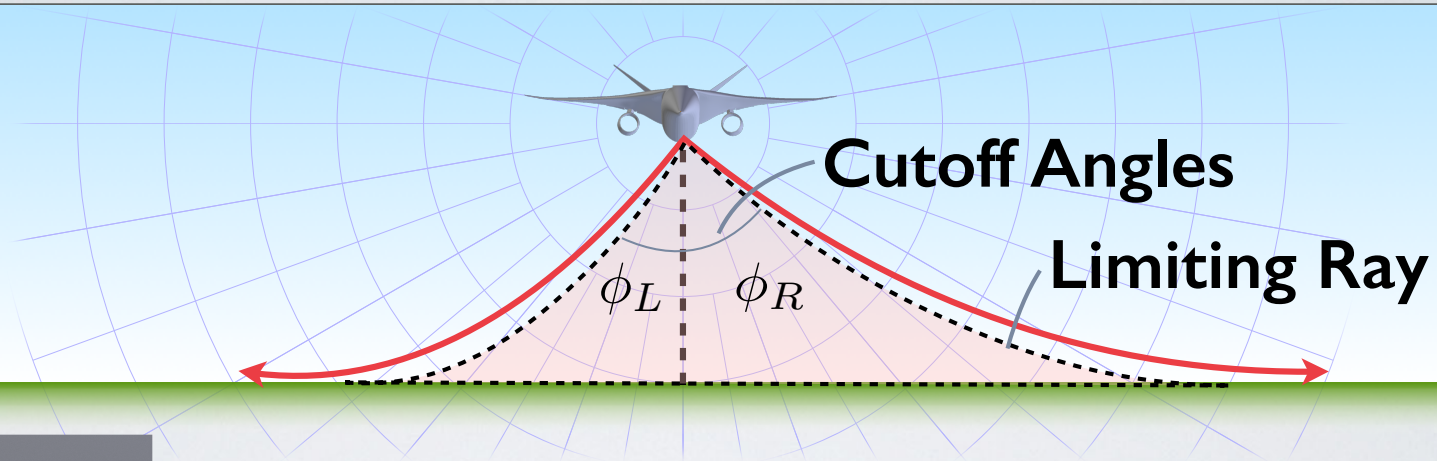
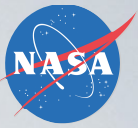
$L_{ref} = 71\text{m (233 ft)}$

Altitude = 16.7 km (~55K ft)

Profiles:

- ISO Standard Atmosphere
- ISO Std. Atm. with 70% humidity
- 2 consecutive winter days in Green Bay, WI

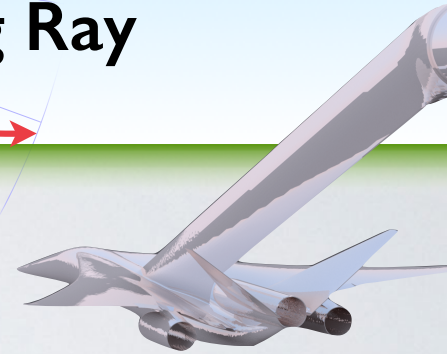
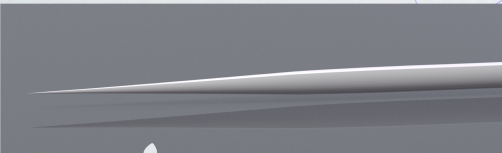
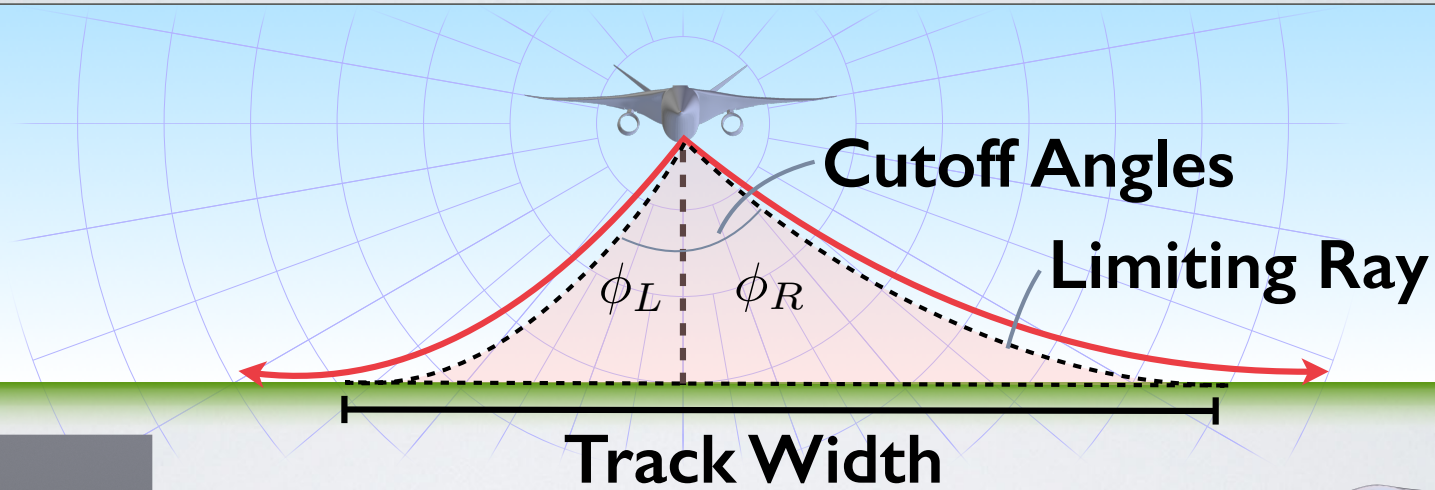
BOOM FOOTPRINT



AXIE	Cutoff	
Std. Atm	$\pm 50^\circ$	
Atm # 3	-53°	50°
Atm # 4	-44°	47°

LM-1021	Cutoff	
Std. Atm	$\pm 50^\circ$	
Atm # 1	-74°	57°
Atm # 2	-59°	65°

BOOM FOOTPRINT



AXIE

Cutoff

Track Width

Std. Atm

$\pm 50^\circ$

69 km

Atm # 3

-53°

50°

85 km

Atm # 4

-44°

47°

72 km

LM-1021

Cutoff

Track Width

Std. Atm

$\pm 50^\circ$

71 km

Atm # 1

-74°

57°

87 km

Atm # 2

-59°

65°

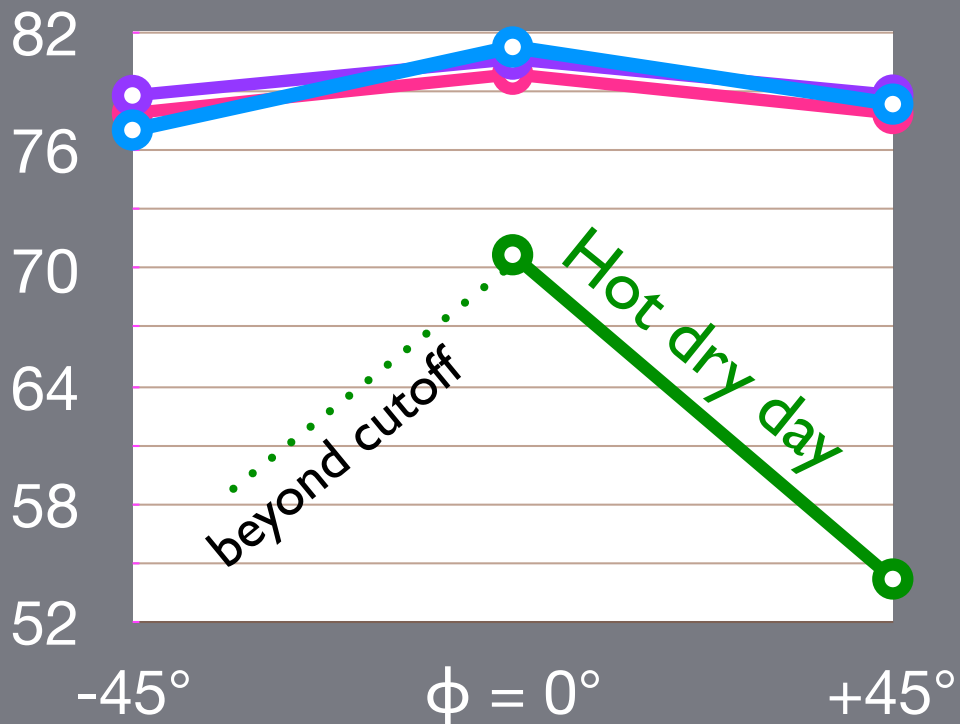
111 km

LOUDNESS

AXIE

PLdB*

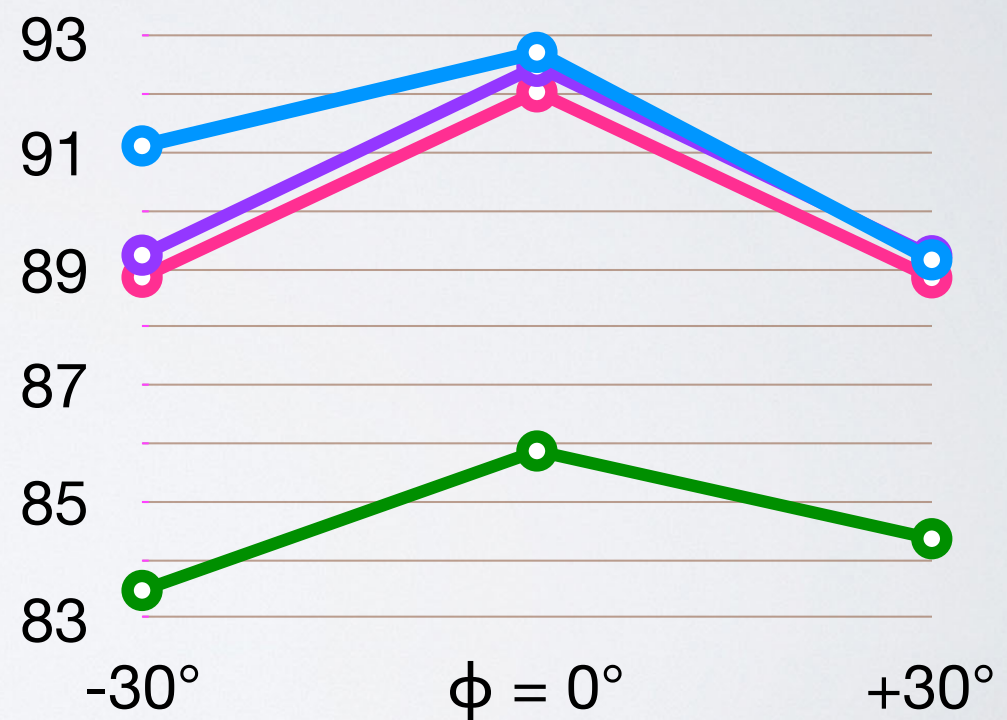
- Atm #3
- Std. Atm
- Atm #4
- Std. Atm+70%RH



LM-1021

PLdB

- Atm #1
- Std. Atm
- Atm #2
- Std. Atm+70%RH



*(1991) Shepherd & Sullivan, "A Loudness Calculation Procedure Applied to Shaped Sonic Booms"

- ✓ **Nearfield Workshop**
- ✓ **Propagation Workshop — sBOOM**
- ▶ **Full Vehicle-to-Boom Simulation Path**
 - Propagate nearfield CFD signatures through standard atmosphere
 - Overall convergence and accuracy
- **Conclusions**

NEARFIELD + PROPAGATION

Perceived loudness (PLdB)

from $r/L=5$ on fine CFD mesh

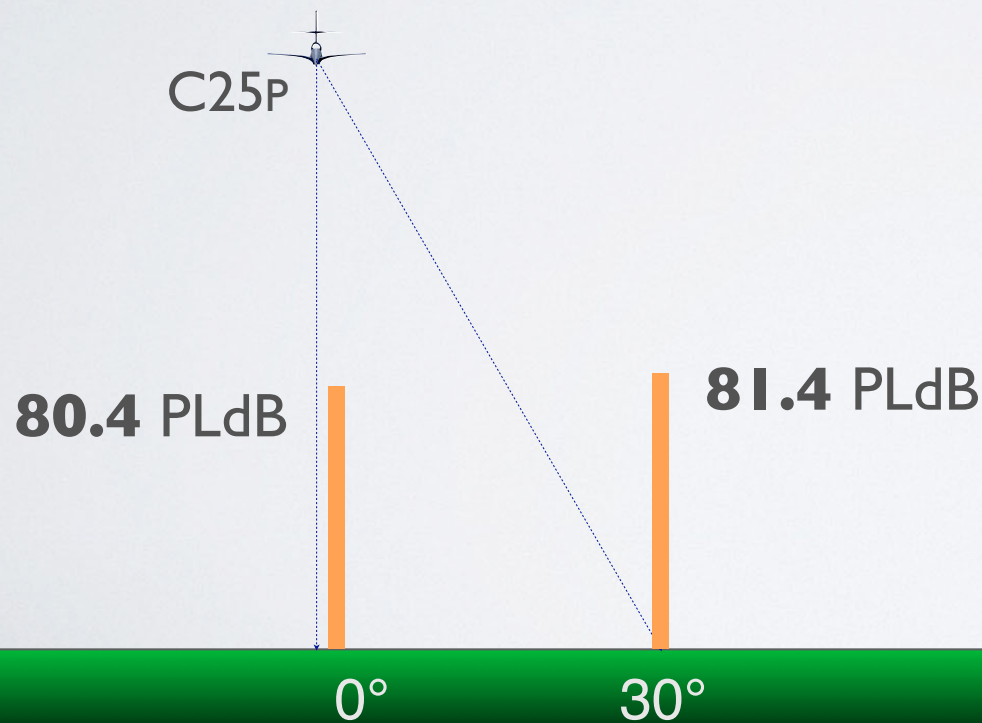
Case	$\Phi = 0^\circ$	$\Phi = 10^\circ$	$\Phi = 20^\circ$	$\Phi = 30^\circ$	$\Phi = 40^\circ$	$\Phi = 50^\circ$
AXIE	78.1	—	—	—	—	—
JWB	79.5	76.5	78.2	82.2	81.6	76.6
C25F	78.1	80.4	80.1	82.2	80.1	73.3
C25P	80.4	81.3	78.3	81.4	78.7	73.3

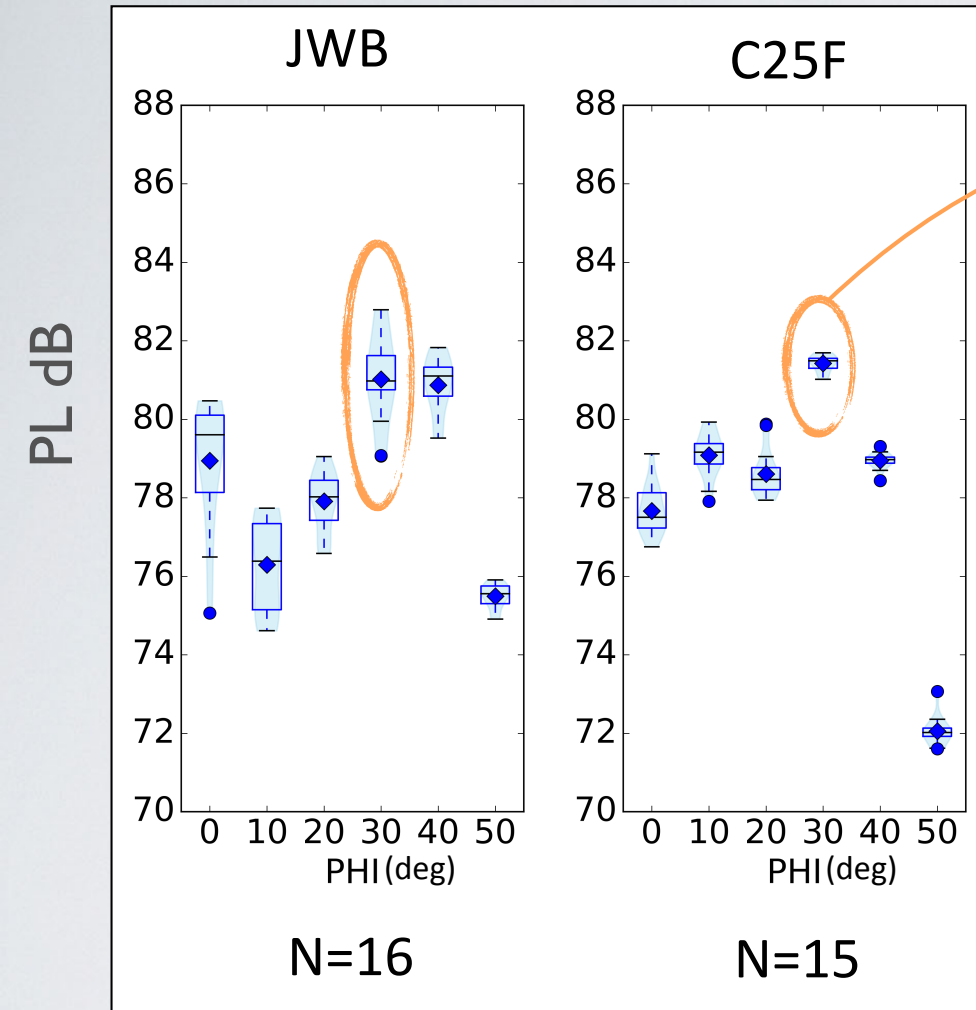
NEARFIELD + PROPAGATION

Perceived loudness (PLdB)

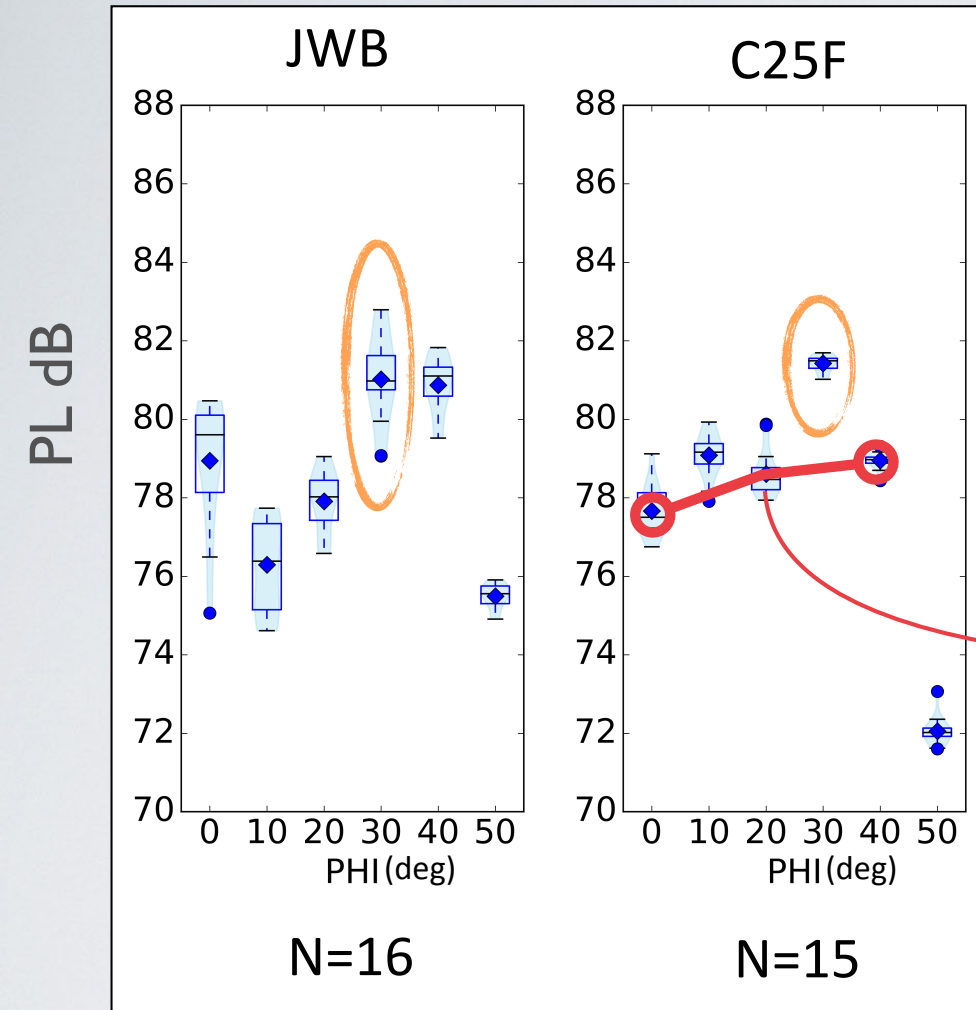
from $r/L=5$ on fine CFD mesh

Case	$\Phi = 0^\circ$	$\Phi = 10^\circ$	$\Phi = 20^\circ$	$\Phi = 30^\circ$	$\Phi = 40^\circ$	$\Phi = 50^\circ$
AXIE	78.1	—	—	—	—	—
JWB	79.5	76.5	78.2	82.2	81.6	76.6
C25F	78.1	80.4	80.1	82.2	80.1	73.3
C25P	80.4	81.3	78.3	81.4	78.7	73.3





(2017) Park and Nemec, *“Nearfield Summary and Statistical Analysis of the Second AIAA Sonic Boom Prediction Workshop”*



Off-track boom is not just relevant, but critical!

A coarser carpet discretization ($\Delta\Phi=20^\circ$) would have under-predicted the worst boom by ~ 3 dB!

(2017) Park and Nemec, “*Nearfield Summary and Statistical Analysis of the Second AIAA Sonic Boom Prediction Workshop*”

CFD MESH CONVERGENCE OF LOUDNESS

Perceived loudness (PLdB)

from $r/L=5$ on fine CFD mesh

Case	$\Phi = 0^\circ$	$\Phi = 10^\circ$	$\Phi = 20^\circ$	$\Phi = 30^\circ$	$\Phi = 40^\circ$	$\Phi = 50^\circ$
AXIE	78.1 (0.4)	—	—	—	—	—
JWB	79.5 (0.6)	76.5 (0.7)	78.2 (0.4)	82.2 (1.5)	81.6 (0.1)	76.6 (0.5)
C25F	78.1 (0.8)	80.4 (0.6)	80.1 (0.1)	82.2 (0.8)	80.1 (0.6)	73.3 (0.0)
C25P	80.4 (0.5)	81.3 (0.5)	78.3 (0.3)	81.4 (0.6)	78.7 (0.4)	73.3 (1.6)

$\Delta PLdB$ from coarse to fine CFD mesh

- Typically **<1 dB change** from coarse to fine CFD mesh (max 1.6 dB)

CFD MESH CONVERGENCE OF LOUDNESS

Perceived loudness (PLdB)

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$\Delta PLdB$ from coarse to fine CFD mesh

- Typically < 1 dB change from coarse to fine CFD mesh (max 1.6 dB)
- Most do not demonstrate **asymptotic** convergence.
- Summary results indicate similar behavior across many codes

CFD functional

$$\mathcal{J}_r = \int_0^L w(\ell) \left(\frac{p(\ell) - p_\infty}{p_\infty} \right)^2 d\ell$$

used as a convenient
surrogate for loudness

▶ **Improving CFD/Propagation Coupling**

- ▶ Better understanding the CFD meshing requirements
- ▶ Using noise sensitivities to guide CFD mesh adaptation (direct adaptation to noise vs. surrogate functionals)
- ▶ Better interpolation/transfer of signatures

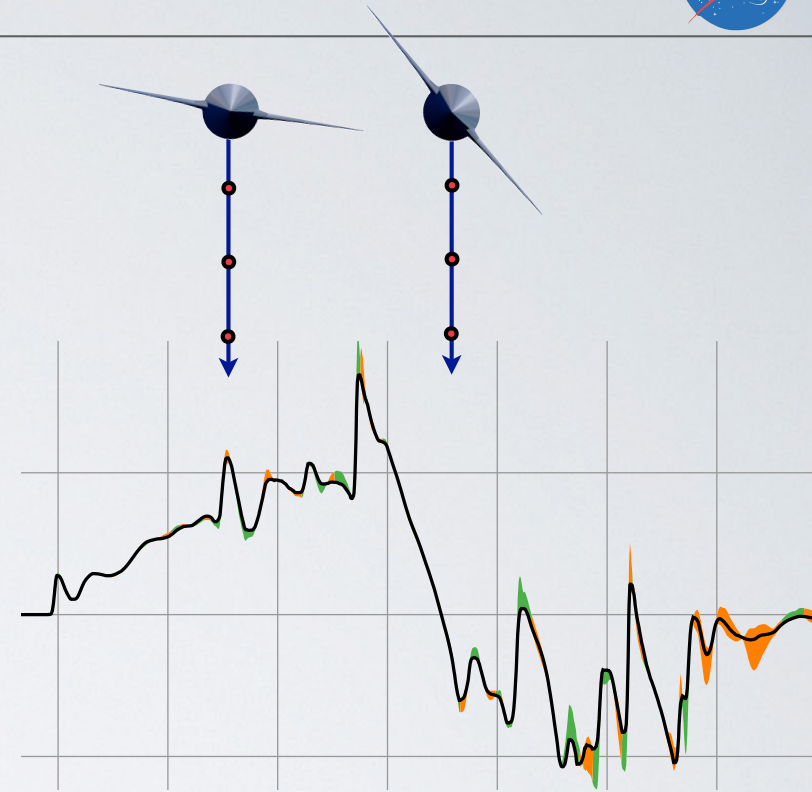
▶ **Physics**

- ▶ Wake unsteadiness
- ▶ Maneuver, elastic effects, control surfaces
- ▶ Propagation — secondary booms, reflections

HIGHLIGHTS

Nearfield with Cart3D

- ▶ Improved efficiency by carpet splitting, azimuthal alignment, and stretching
- ▶ Method for assessing local signature mesh convergence *[scripts available]*



HIGHLIGHTS

Nearfield with Cart3D

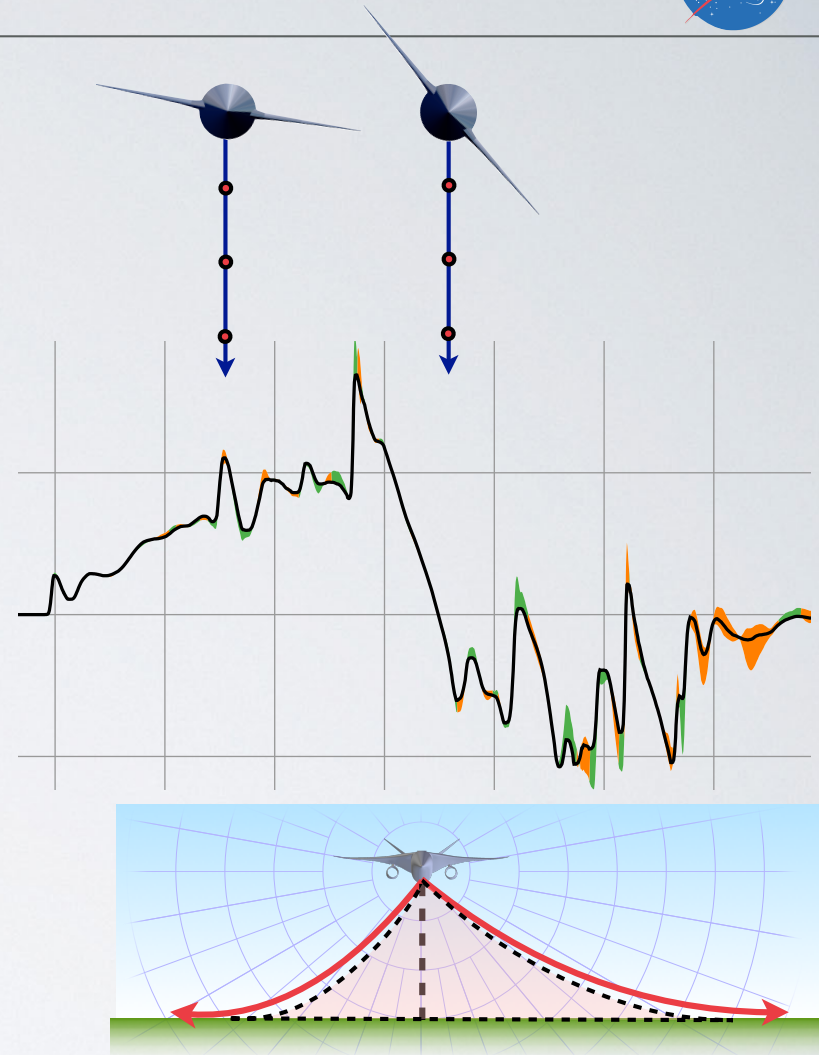
- ▶ Improved efficiency by carpet splitting, azimuthal alignment, and stretching
- ▶ Method for assessing local signature mesh convergence [*scripts available*]

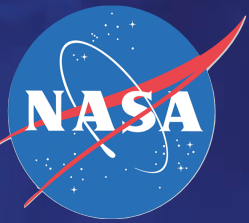
Propagation with sBOOM

- ▶ Major atmospheric variability: 2-5 dB typical, 10-20 dB in extreme cases.
- ▶ With cross-wind, **75° off-track** can hit ground, **track widths widen by 50%**

Full Boom Simulation Path

- ▶ Need to better understand asymptotic convergence of noise





QUESTIONS?



George R. Anderson

Science & Technology Corp.
george.anderson@nasa.gov

Michael J. Aftosmis

NASA Ames
michael.aftosmis@nasa.gov

Marian Nemec

NASA Ames
marian.nemec@nasa.gov

NASA Ames Computational Aerosciences Branch

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